



**Institute of
Applied Physics**

Friedrich-Schiller-Universität Jena

Optical Design with Zemax for PhD - Advanced

Seminar 8 : Tolerancing I

2015-01-21

Herbert Gross



No	Date	Subject	Detailed content
1	12.11.	Repetition	Correction, handling, multi-configuration
2	19.11.	Illumination I	Simple illumination problems
3	26.11.	Illumination II	Non-sequential raytrace
4	03.12.	Physical modeling I	Gaussian beams, physical propagation
5	10.12.	Physical modeling II	Polarization
6	07.01.	Physical modeling III	Coatings
7	14.01.	Physical modeling IV	Scattering
8	21.01.	Tolerancing I	Sensitivity, practical procedure
9	28.01.	Tolerancing II	Adjustment, thermal loading, ghosts
10	04.02.	Additional topics	Adaptive optics, stock lens matching, index fit, Macro language, coupling Zemax-Matlab

1. Introduction
2. Tolerances – general aspects
3. Statistics and compensators
4. Form tolerances
5. Material tolerances
6. Centering tolerances
7. Mechanical design and mountings
8. Tolerancing in Zemax

- Specifications are usually defined for the as-built system
- Optical designer has to develop an error budget that cover all influences on performance degradation as
 - design imperfections
 - manufacturing imperfections
 - integration and adjustment
 - environmental influences
- No optical system can be manufactured perfectly (as designed)
 - Surface quality, scratches, digs, micro roughness
 - Surface figure (radius, asphericity, slope error, astigmatic contributions, waviness)
 - Thickness (glass thickness and air distances)
 - Refractive index (n-value, n-homogeneity, birefringence)
 - Abbe number
 - Homogeneity of material (bubbles and inclusions)
 - Centering (orientation of components, wedge of lenses, angles of prisms, position of components)
 - Size of components (diameter of lenses, length of prism sides)
 - Special: gradient media deviations, diffractive elements, segmented surfaces,...
- Tolerancing and development of alignment concepts are essential parts of the optical design process

Sensitivity of a System



- Sensitivity/relaxation:
Average of weighted surface contributions
of all aberrations

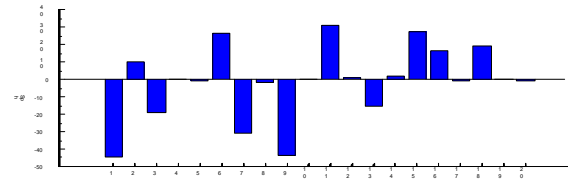
- Correctability:
Average of all total aberration values

- Total refractive power

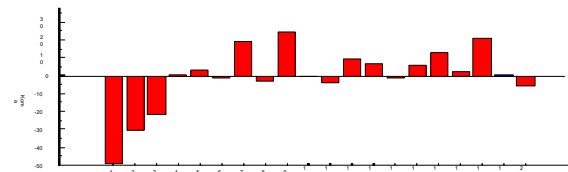
$$F = F_1 + \sum_{j=2}^k \omega_j F_j$$

- Important weighting factor:
ratio of marginal ray heights

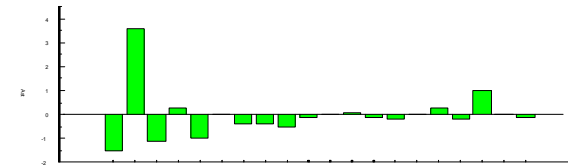
$$\omega_j = \frac{h_j}{h_1}$$



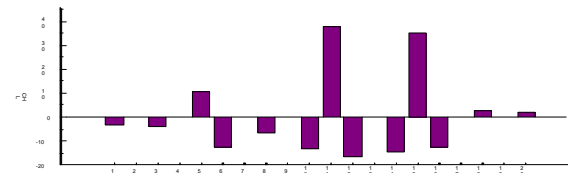
Sph



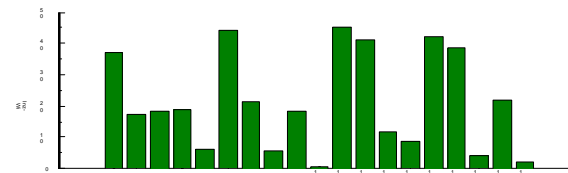
Coma



Ast



CHL



incidence
angle

- Quantitative measure for relaxation

$$A_j = \omega_j \cdot \frac{F_j}{F} = \frac{h_j \cdot F_j}{h_1 \cdot F}$$

with normalization $\sum_{j=1}^k A_j = 1$

- Non-relaxed surfaces:
 1. Large incidence angles
 2. Large ray bending
 3. Large surface contributions of aberrations
 4. Significant occurrence of higher aberration orders
 5. Large sensitivity for centering
- Internal relaxation can not be easily recognized in the total performance
- Large sensitivities can be avoided by incorporating surface contribution of aberrations into merit function during optimization

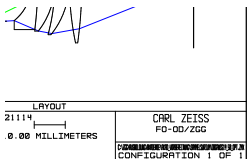
Sensitivity of a System



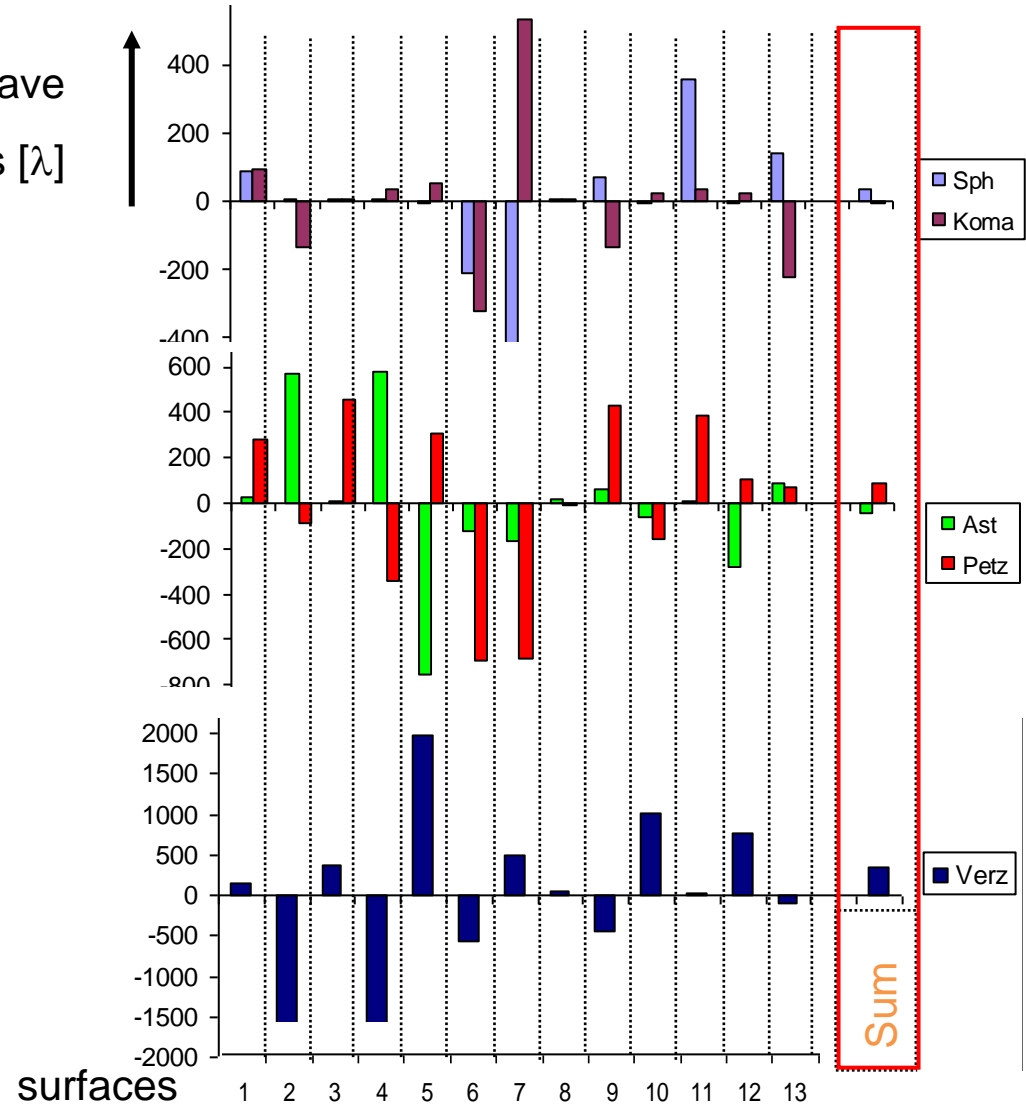
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Representation of wave
Seidel coefficients [λ]

Double Gauss 1.4/50



1 2 3 4 5 6 7 8 9 10 11 12 13



surfaces

Ref: H.Zügge

- Standard ISO-10110

ISO 10110-2	Material imperfections – stress birefringence
ISO 10110-3	Material imperfections – bubbles and inclusions
ISO 10110-4	Material imperfections – inhomogeneity and striae
ISO 10110-5	Surface-form tolerances
ISO 10110-6	Centering tolerances
ISO 10110-7	Surface-imperfection tolerances
ISO 10110-8	Surface texture
ISO 10110-9	Surface treatment and coating

- Data for mechanical design, development and manufacturing:
- Data sheet with standard data/numbers of system and tolerances
- Additional support data (optional) :
 1. Prisms, plano components, test procedures
 2. Adjustment and system integration
 3. Centering for cementing
 4. Centering for mechanics
 5. Coatings
 6. Geometrical dimensions / folding mirrors
 7. Test procedures and necessary accuracies
 8. Auxiliary optics for testing
 9. Combination of tolerances
 10. Zoom curves and dependencies
 11. Adaptive control data
 12. Interface to connected systems

Data Sheet



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ZEISS										OBERKOCHEN: RECHNUNG VOM xxx										ABT. xxxxx			
										ZEICHNUNG : Ø										KOMIKRO			
DATEN: BETA =-99.6 X1 =UNENDL. F2,3=+ 4.0MM F8,9 =-35. F1-16=+ 1.66MM X16'=-8.59MM F4,5=+102.3MM F9,10=+10. 0-0' =195.0MM 0-S16=38.21MM F6,7=+ 17.3MM F8-10=+15.										MIKRO 63D13415										KØ HERAUSGEGEBEN AM 26.6.91		FO-EM-M/MUCH	
RADIUS			PLAN	PLAN	2.0700	2.6550	3.2210	13.428	6.3100														
SKIZZE																							
TEIL NR.																							
2H			Ø.5	1.5	3.9	4.5	6.2	8.7	9.4														
FREIER Ø			1.5	1.5	3.9	4.5	6.2	8.7	9.4														
Ø																							
GLASART			K5	IMOEL	K7		LAK11		PSK53A														
SCHMELZE																							
(587.6 nm)			1.52249	1.51500	1.51112		1.65830		1.62014														
STUFE			±0.001 (4)		±0.0003 (2)		±0.0005 (3)		±0.0005 (3)														
Ud			59.48	43.45	60.41		57.26		63.48														
STUFE			±0.8 % (4)		±0.5 % (3)		±0.5 % (3)		±0.3 % (2)														
TOLERANZEN: KOMBINATIONSFREIE FERTIGUNG																							
D			±0.04		±0.03	±0.05	±0.02	±0.01	±0.02														
KITT																							
Ø) KUEHLUNG			20		20		20		20														
1) BLASEN					1X0.1		1X0.1		1X0.1														
2) SCHLIEREN			-; 2		-; 2		-; 2		-; 2														
3) PASSE					5.0(1.0)	2.0(0.4)	2.0(0.4)	3.0(0.6)	1.0(0.2)	1.0(0.2)													
4) ZENTR.					9'	6'	8'	6'	2'	2'													
5) UNSAUB.	3415				1X0.04	1X0.1	1X0.1	1X0.1	1X0.16	1X0.16													

- Surface quality, scratches, digs, micro roughness
- Surface figure
radius, asphericity, slope error, astigmatic contributions, waviness
- Thickness
glass thickness and air distances
- Refractive index
n-value, n-homogeneity, birefringence
- Abbe number
- Homogeneity of material
bubbles and inclusions
- Centering:
orientation of components, wedge of lenses, angles of prisms, position of components
- Size of components
diameter of lenses, length of prism sides
- Special:
gradient media deviations, diffractive elements, segmented surfaces,...

Tolerances: Typical Values

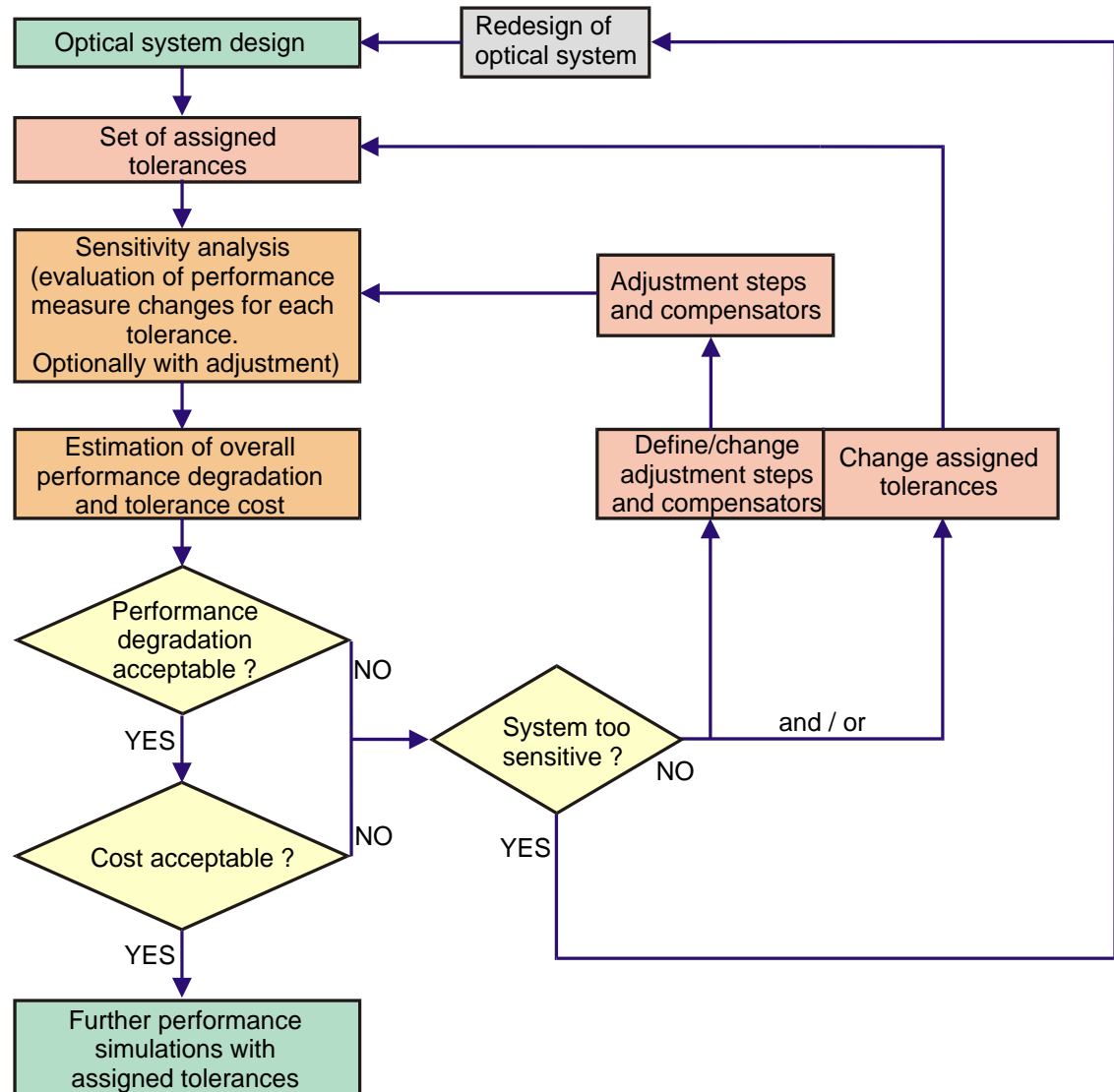


Diameter	Tolerance	Unit	<10 mm	10...20 mm	20...30 mm
Center thickness		mm	0.02	0.03	0.03
Centering	Tilt angle	sek	60	60	60
	Decenter/offset	μm	15	15	15
Roughness		nm	15	10	10
Spherical/radius	spherical	rings	3	4	5
	astigmatism	rings	.5	1	1
Asphericity	Global deviation	μm	1	1.2	1.5
	Global asphericity	μm	0.25	0.45	0.60
	Local deviation	μm	0.025	0.05	0.075
	Slope error	rad	0.0005	0.0005	0.0005

Tolerance Analysis by Sensitivities

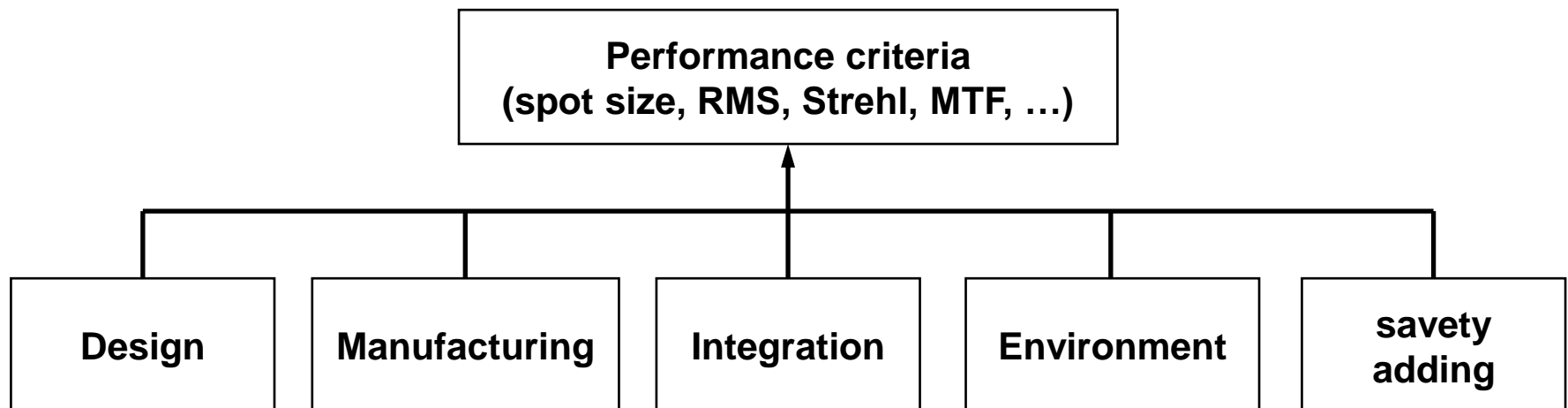


- Systematic finding of tolerances



- Selection of the performance criterion,
spot size, rms wavefront, MTF, Strehl,...
- Choice of the allowed degradation of performance, limiting maximum value of the criterion
- Definition of compensators for the adjustments
image location, intermediate air distances, centering lenses, tilt mirrors,...
- Calculation of the sensitivities of all tolerances:
influence of all tolerances on all performance numbers
- Starting the tolerance balancing with proper default values,
alternatively inverse sensitivity: largest amount of deviation for the accepted degradation
- Tolerance balancing:
calculating all tolerances individually to keep the overall performance with technical
realistic accuracies of the parameter

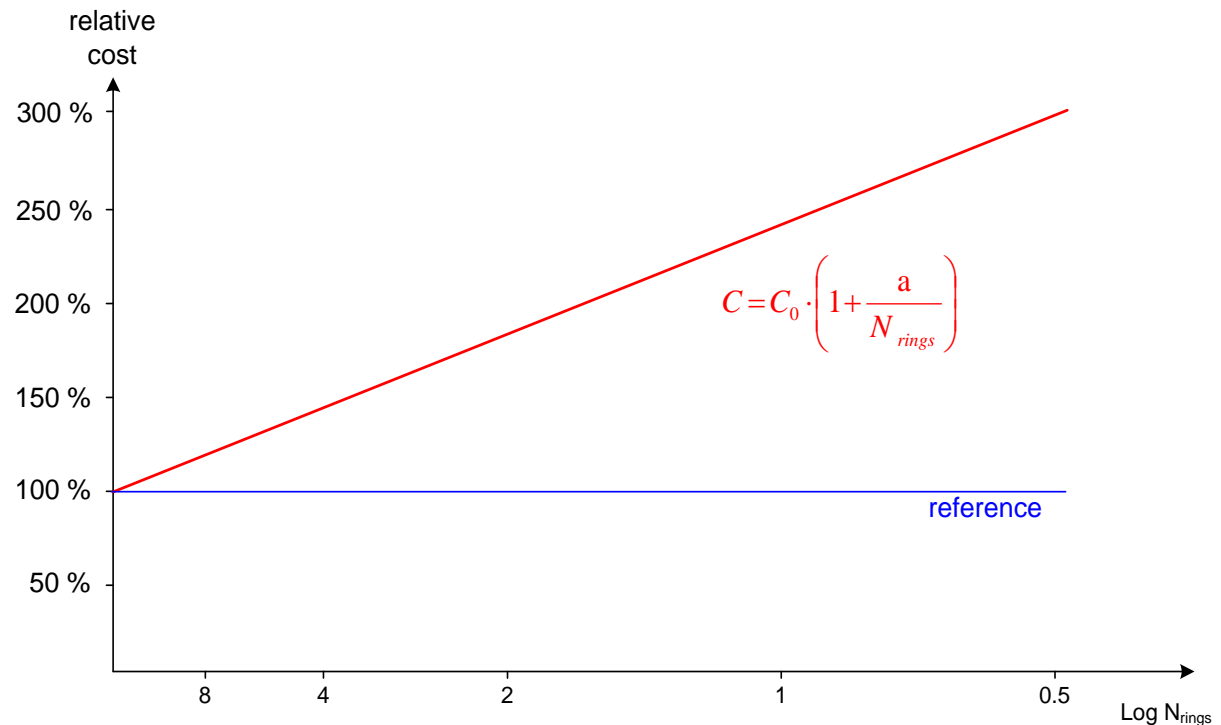
- Sources of errors:
 - materials
 - manufacturing
 - integration/adjustment/mounting
 - environmental influences
 - residual design aberrations
- Performance evaluation:
 - selection of proper criterion
 - fixation of allowed performance level
 - calculation of sensitivity of individual tolerances and combined effects (groups, dependent errors)
 - balancing of overall tolerance limits for complete system



Tolerances and Cost Impact



- Typical behavior of the cost function: additive cost
- Exponential growth of cost with decreased tolerance width
- The slope and the reference value depends on type of tolerance and technology of manufacturing
- Special aspects:
 - new manufacturing technologies
 - jumps of cost



Tolerances and Additional Cost

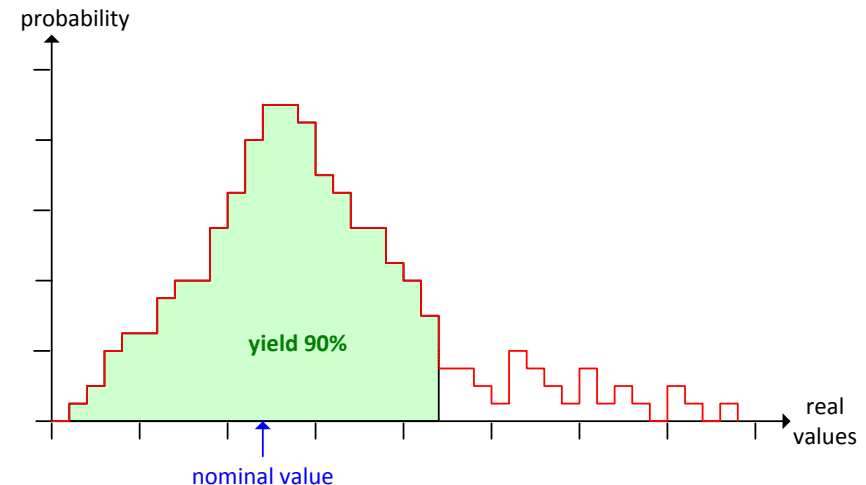


Diameter tolerance in mm	0.1 100 %	0.05 100 %	0.025 103 %	0.0125 115 %	0.0075 150 %	
Thickness tolerance in mm	0.2 100 %	0.1 105 %	0.05 115 %	0.025 150 %	0.0125 300 %	
Centering tolerance in minutes	6' 100 %	3' 103 %	2' 108 %	1' 115 %	30" 140 %	15" 200 %
Shape tolerance as ring number in λ	10 7 5 100 %	5 / 2 105 %	3 / 1 120 %	2 / 0.5 140 %	2 / 0.25 175 %	1 / 0.12 300 %
ratio diameter vs thickness	9 100 %	15 120 %	20 150 %	30 200 %	40 300 %	50 500 %
Scratches and dots (MIL-Norm)	80 / 50 100 %	60 / 40 110 %	40 / 30 125 %	20 / 10 175 %	10 7 5 350 %	
Coating	without 100 %	1 Layer 115 %	3 Layer 150 %	Multilay. < 500 %		

- Evaluation of the complete system:
additive effect of all tolerances, taking partial compensations due to sign and statistics into account
- Worst case superposition:
 - adding all absolute amounts of degradations
 - usually gives to costly and tight tolerances
 - no compensations considered, to pessimistic
- Rms mean superposition:
 - approach with ideal statistics and quadratic summation
 - compensations are taken into account approximately
 - real world statistics is more complicated
 - deterministic effects of adjustments are not considered
- Calculation of Monte Carlo statistics with deterministic adjustment steps
 - best practice approach
 - statistical distribution can be adapted to experience
 - problems with small number manufacturing

$$\Delta f = \sum_j |\Delta f_j|$$

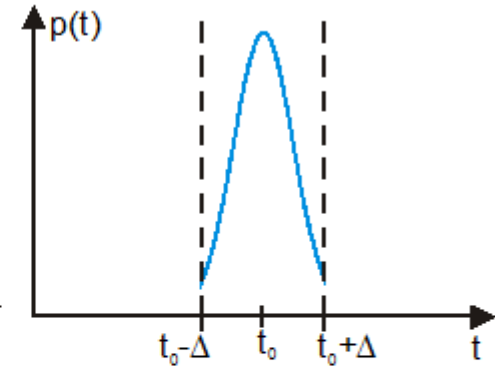
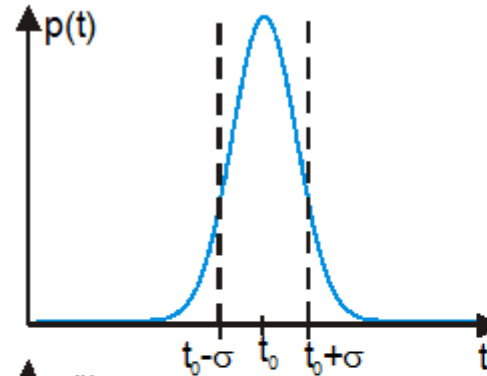
$$\Delta f = \sqrt{\sum_j |\Delta f_j|^2}$$



- Gaussian

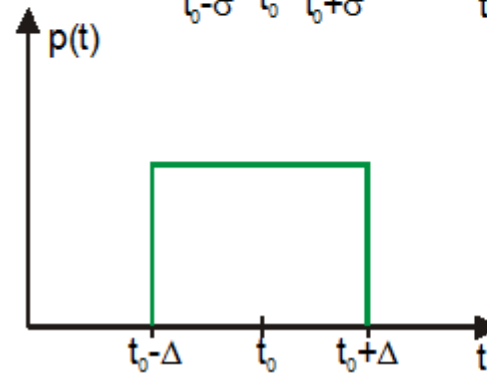
$$p(t) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(t-t_0)^2}{2\sigma^2}}$$

- Truncated Gaussian



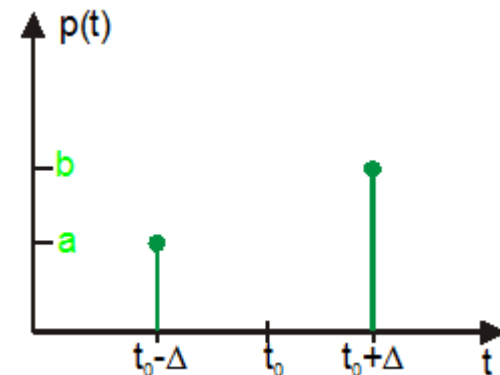
- Uniform

$$p(t) = \frac{1}{2\Delta} \quad , \quad t_0 - \Delta \leq t \leq t_0 + \Delta$$



- Ping-pong

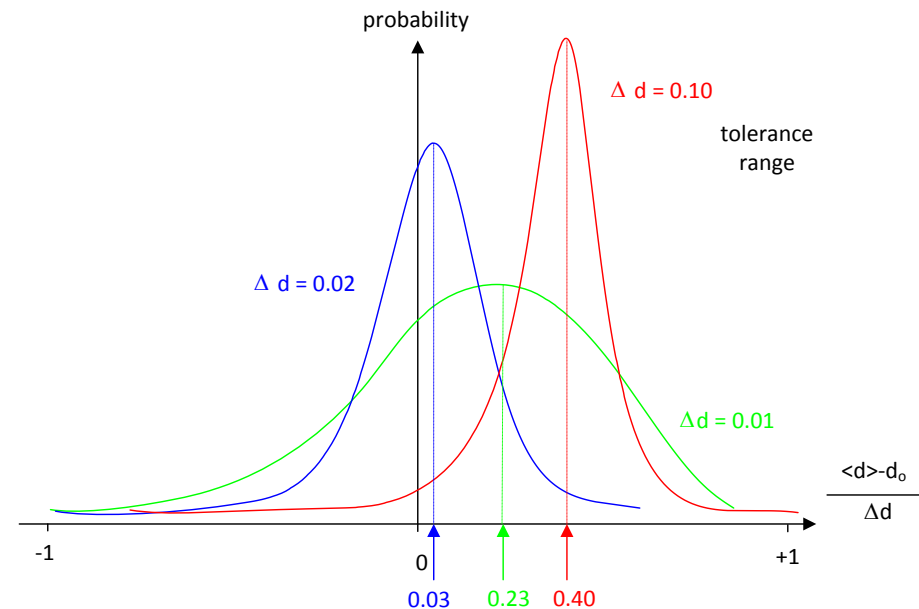
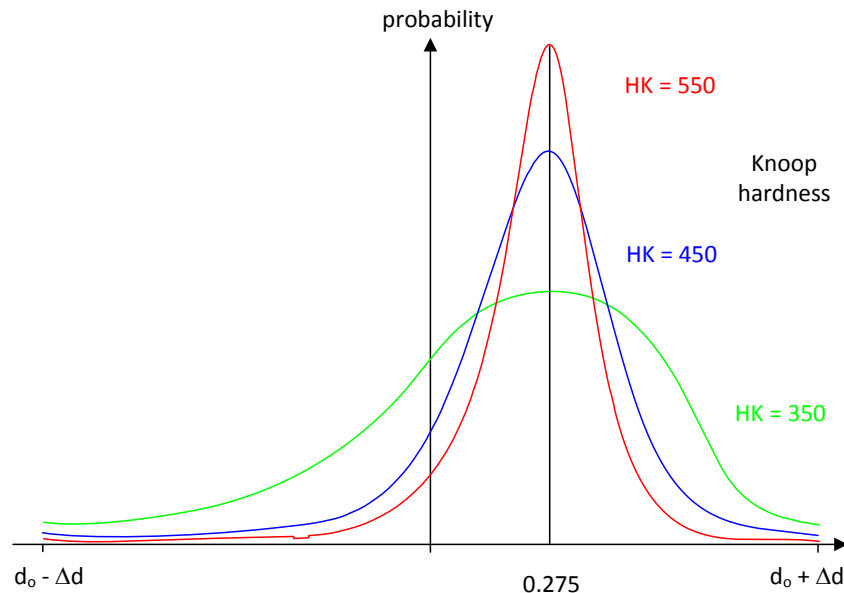
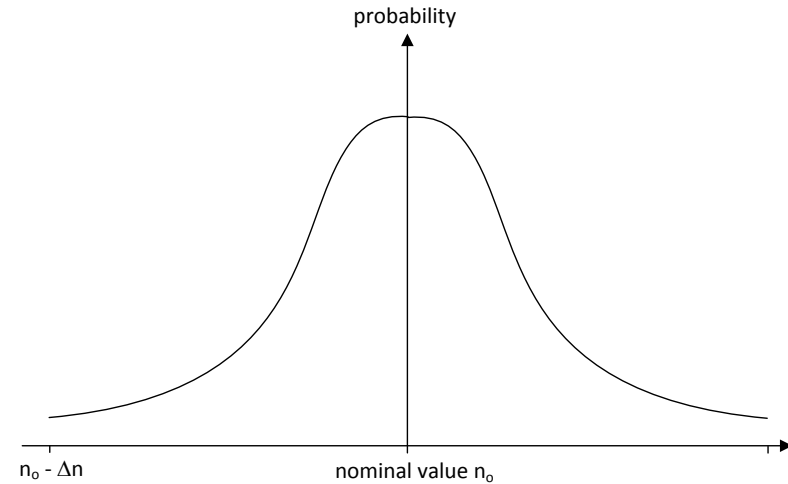
$$p(t) = \frac{1}{a+b} [a \cdot \delta(t - t_0 + \Delta) + b \cdot \delta(t - t_0 - \Delta)]$$



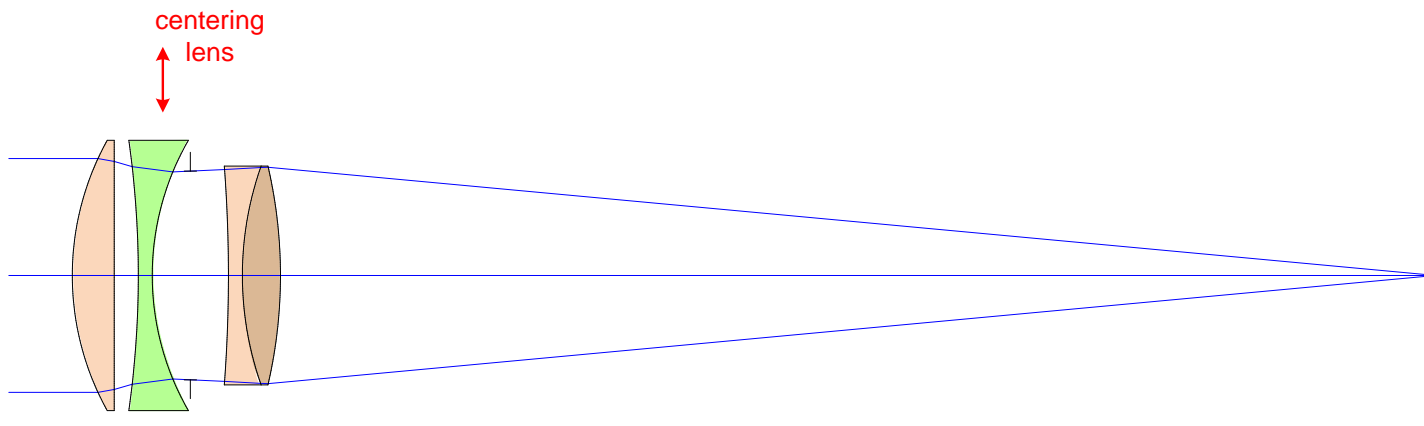


Tolerances and Statistics

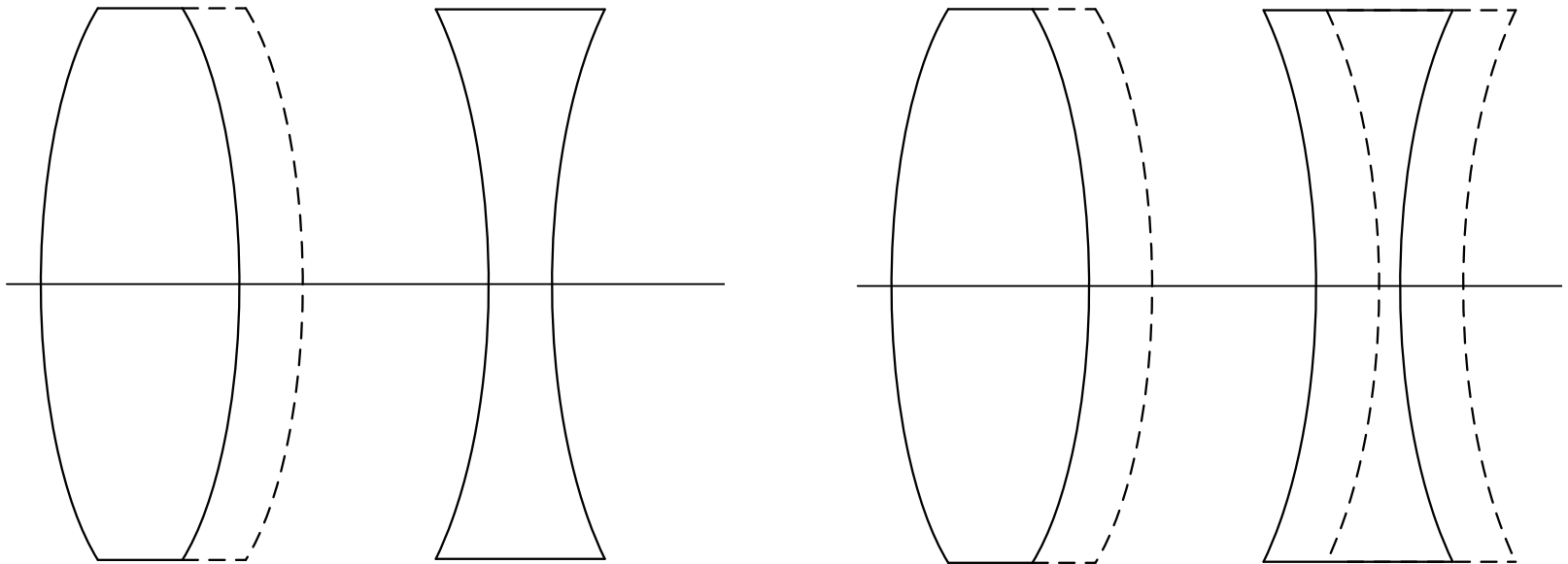
- Statistics of refractive index tolerances:
nearly normal distributed
- Tolerances of lens thickness:
 - biased statistical distribution with mean at $0.3 \Delta d$
 - less pronounced offset for small intervals of tolerance
 - width of the distribution depends on the hardness of the material



- Compensators:
 - changeable system parameter to partly compensate the influence of tolerances
 - compensators are costly due to an adjustment step in the production
 - usually the tolerances can be enlarged, which lowers the cost of components
 - clever balance of cost and performance between tolerances and adjustment
- Adjustment steps should be modelled to learn about their benefit, observation of criterias, moving width,...
- Special case: image position
compensates for tolerances of radii, indices, thickness
- Centering lenses:
lateral shift of one lens to get a circular symmetric point spread function on axis
- Adjustment of air distances between lenses to adjust for spherical aberration, afocal image position,...

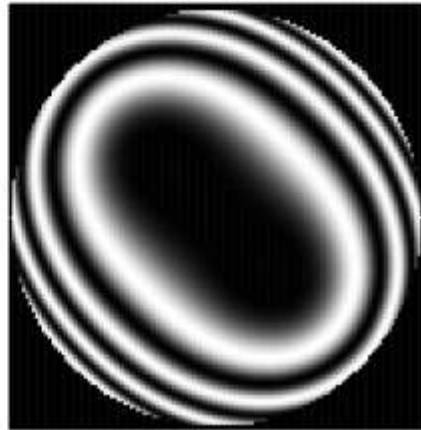
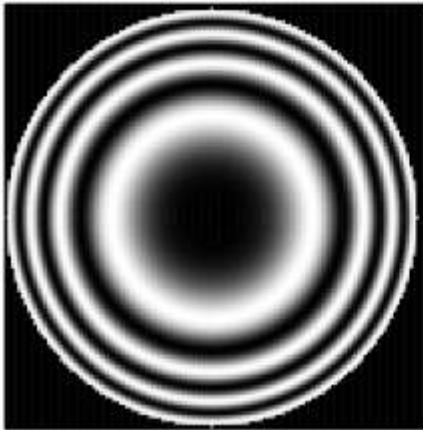
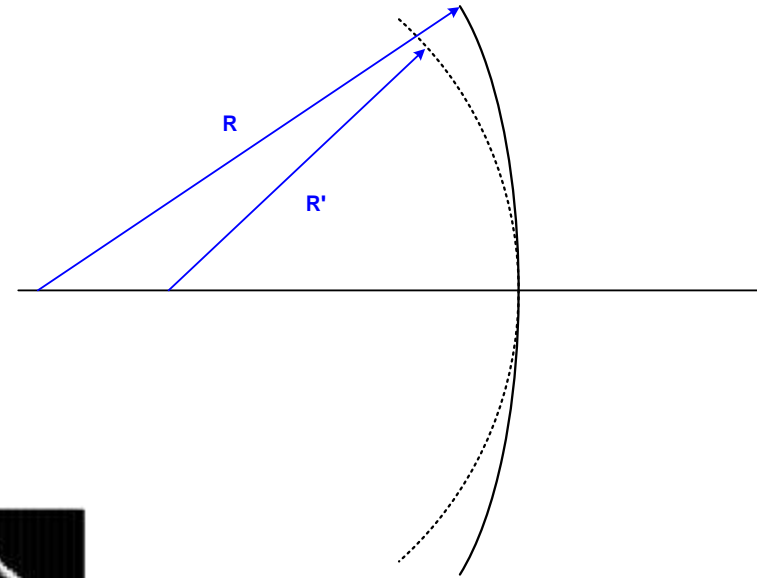


- Tolerances of thickness or distances
- in case of glass thickness: effect of tolerance depends on the mounting setup, the difference usually is added or subtracted in the neighboring air distance
- usually, the overall length of the system remains constant
- the thickness tolerance is far less sensitive as curvature errors



Tolerance of the surface shape:

- specification in fringes
- interferometric measurement
- irregularity: deviation from spherical shape
- typical specification:
5(1) waves: 5 ring 1 spherical deviation
1 ring asymmetry/astigmatism



- Conventional tolerance:
 1. error of radii, can be compensated by defocussing
 2. irregularity, astigmatism
 3. higher order spherical errors like 4th order edge errors
- Slope errors:
 1. relevant error from viewpoint of optical influence
 2. reference basis length necessary for specification to fix spatial frequency
 3. diversification by tolerancing different diameter ranges
- Sag error of the real surface
 1. not appropriate tolerance without specification of the basis length (spatial frequency)
 2. rms number more significant than pv value
- Micro roughness:
 1. high frequent errors due to manufacturing, causes wide angle scattering
 2. specification as rms tolerance
 3. influences contrast

Typical errors of aspherical surfaces

1. long range figure errors
2. high frequency micro roughness

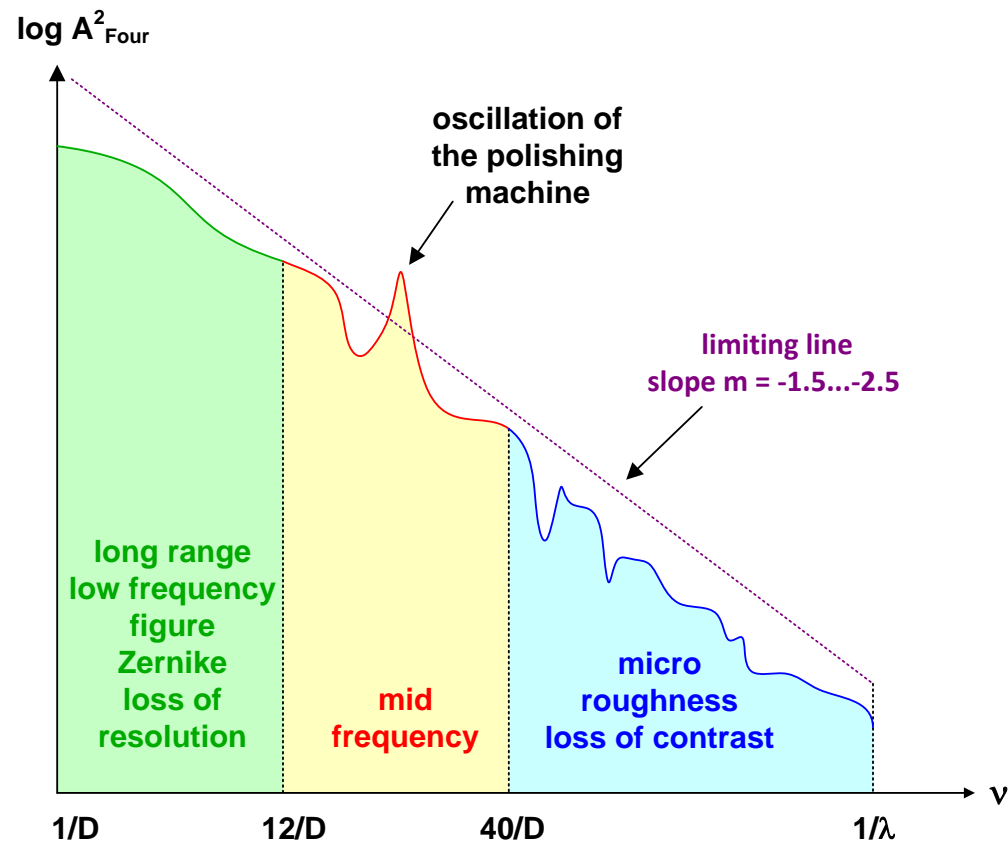
Application	Figure error Rms [nm]	Micro roughness Rms [nm]
Eye glasses	2000	10
Illumination systems	300	2
Digital projection	300	1
Photographic lenses, cameras, consumer	100	1
Satellite systems	20	0.5
DUV – Lithography lenses	2	0.3
EUV – Lithography lenses	0.1	0.1

- Today there is only insufficient experience for the tolerancing of free shaped surfaces
- Specification and tolerancing are not standardized
- Possible options are:
 1. rms value
 2. global maximum deviation Δz (peak valley)
 3. Slope error, in components, in various area ranges of the surface
 4. Sinusoidal perturbations with specified intervals, amplitudes to cover the mid-frequency range
 5. Limiting straight line or accepted thresholds in a logarithmic power spectrum representation



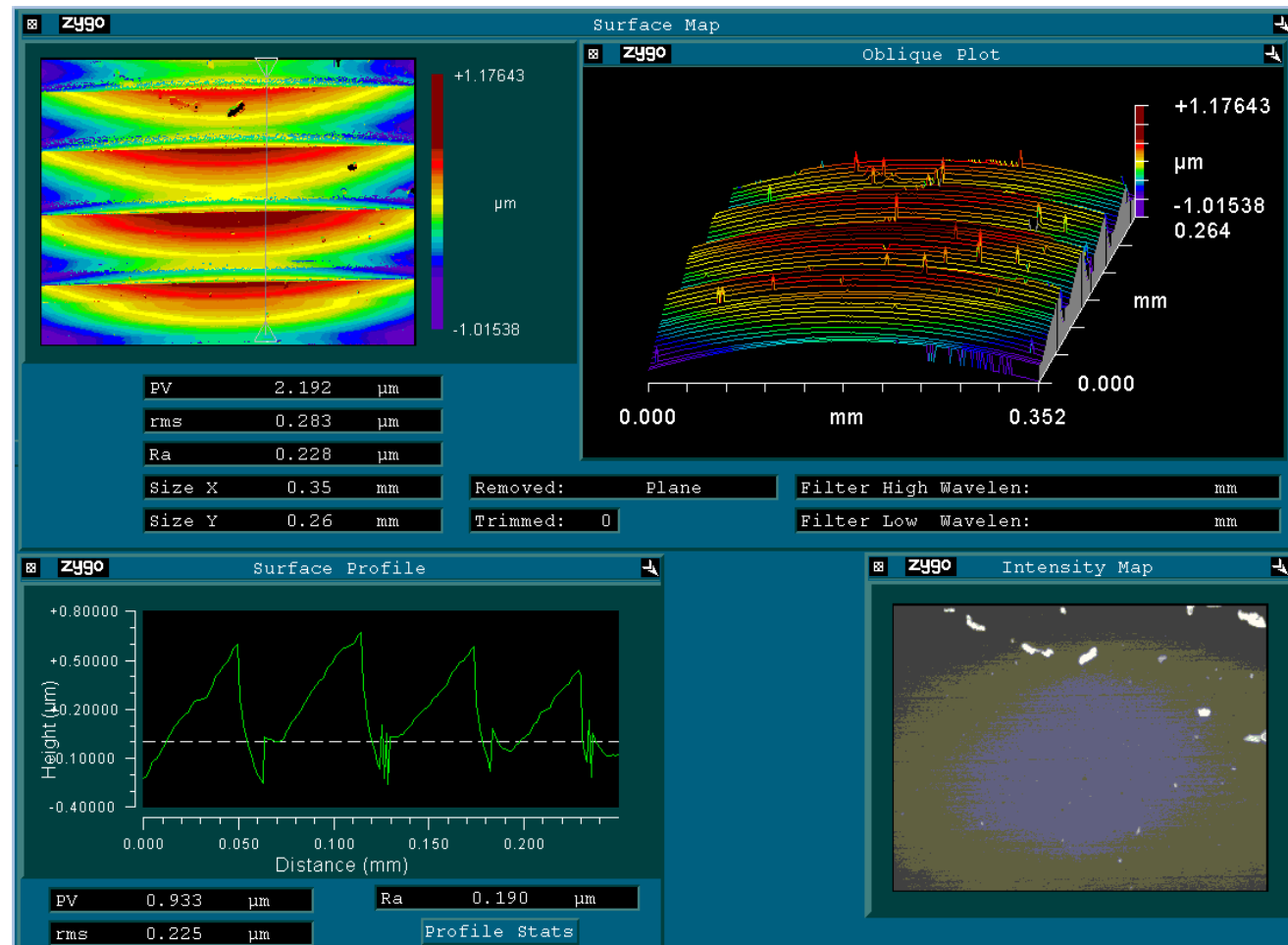
Spatial Frequency Ranges of Surface Errors

- Spatial frequency domain discussion of surface errors
- Power spectral density describes the power in the Fourier components
- Low frequency range:
 - figure error
 - loss in resolution
 - classical aberrations, description by Zernikes
 - interferometric measurement
 - spatial frequency $\nu < 12/D$
- Midfrequency range:
 - ripple due to manufacturing
 - spatial frequency $\nu < 12/D \dots 40/D$
 - reason mostly mechanical perturbations in manufacturing
- High frequency range:
 - micro roughness with high spatial frequencies
 - causes wide angle scattering and straylight
 - reasons are problems with polishing



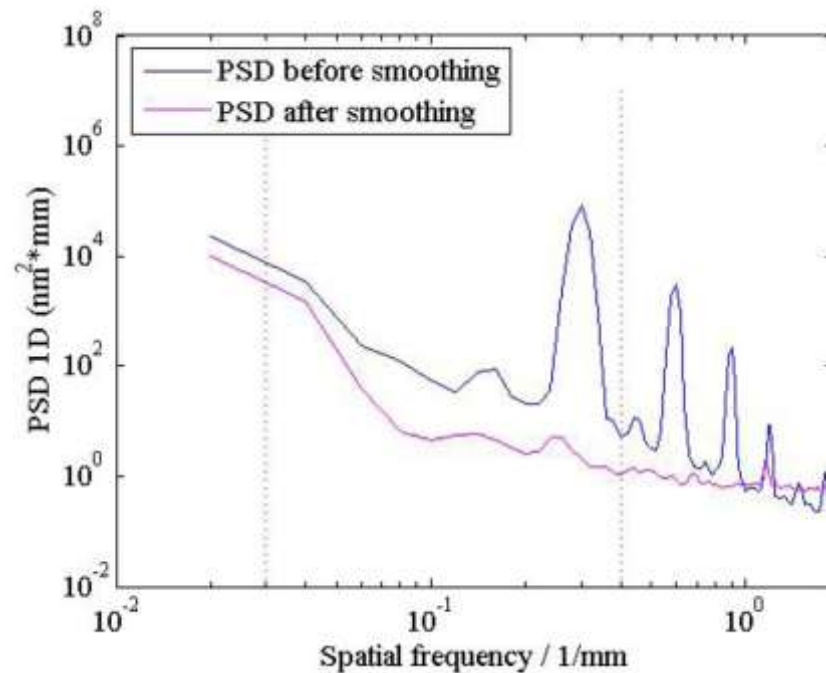
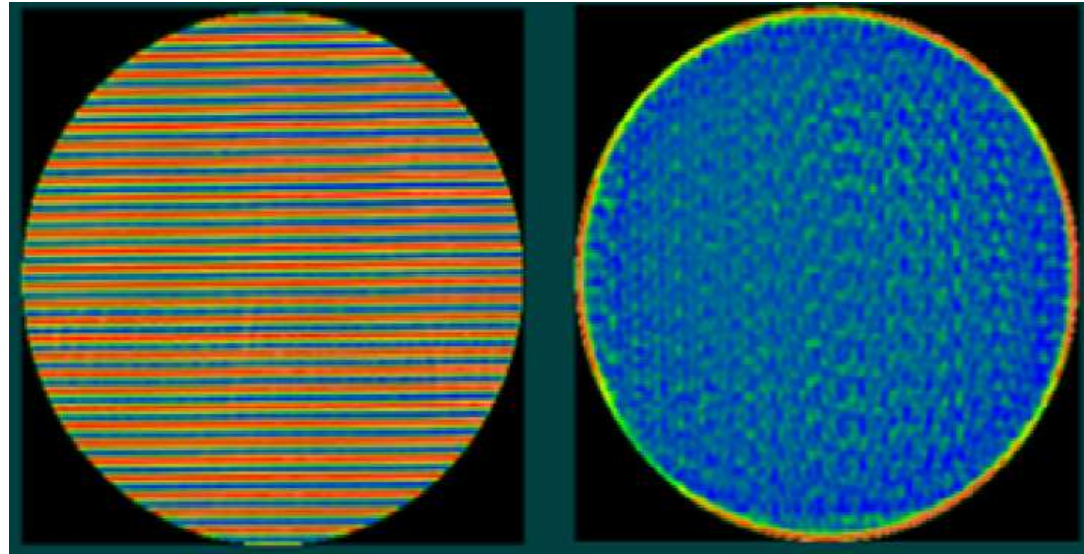
Diamond Turning of Plastic Surfaces

- Structured surface with ripple



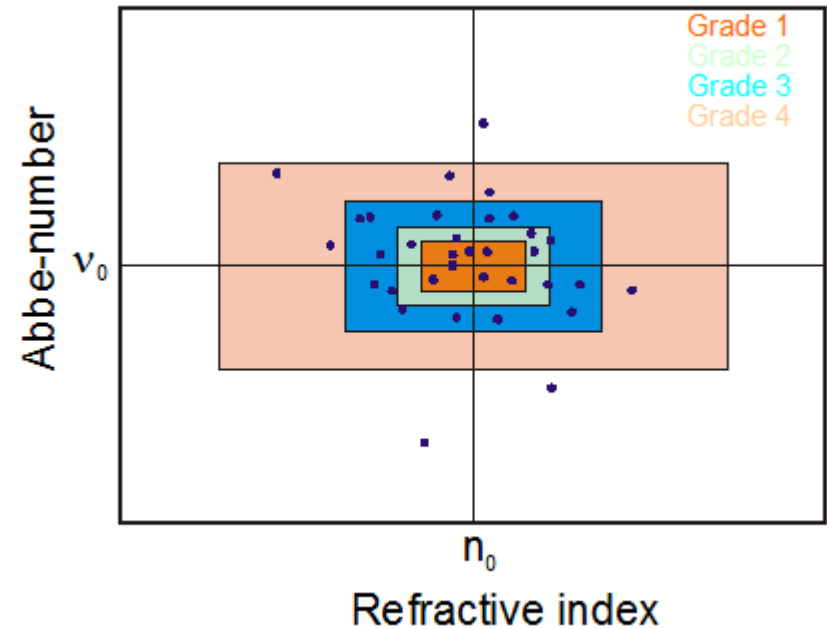
Spatial Midfrequency Errors

- Surface with diamond turning shaping
- Surface and PSD before and after polishing



- Discrete tolerance steps
- Rectangular tolerance areas in n - v plane

Grade (tolerance step)	Δn	$\Delta v / v$
1	+/- 0.0002	+/- 0.2%
2	+/- 0.0003	+/- 0.3%
3	+/- 0.0005	+/- 0.5%
4	+/- 0.001	+/- 0.8%

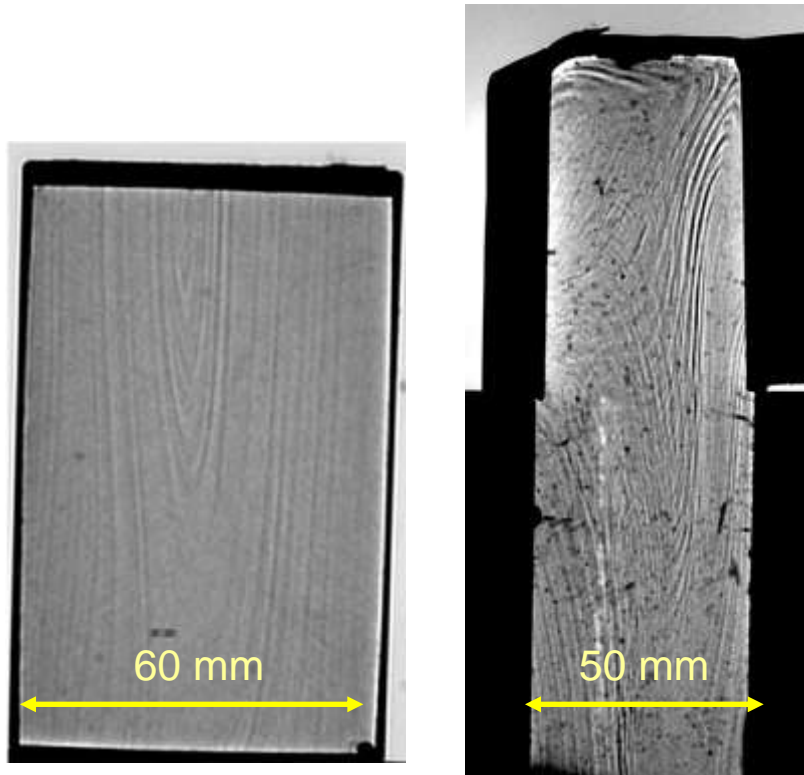


Different classes of homogeneity
of glasses

Class	ISO 10110	Δn in the sample
	0	$50 \cdot 10^{-6}$
	1	$20 \cdot 10^{-6}$
H 2	2	$5 \cdot 10^{-6}$
H 3	3	$2 \cdot 10^{-6}$
H 4	4	$1 \cdot 10^{-6}$
H 5	5	$0.5 \cdot 10^{-6}$

Definition of Striae

- Standard not sufficient
- Appearance:
like wood in transmission shadow image



	MIL-G-174B	DIN ISO 10110-4	SCHOTT (nur intern)	SCHOTT (Katalog)
Gültig für:	Rohglas	Optisches Element	Rohglas	
Charakterisierung durch:	Intensität ohne Beachtung der Probendicke	Schlierendurchsetzte Fläche (Schlierendichte)	Intensität mit Beachtung der Probendicke (50 mm)	
Schlierengrade:	D	$\geq 30 \text{ nm}$ 1: $\leq 10\%$ 2: $\leq 5\%$ 3: $\leq 2\%$ 4: $\leq 1\%$	D: $\sim 60 \text{ nm}$	
	C	5: sehr schwache bis keine Schlieren sichtbar	C: $\sim 30 \text{ nm}$	$< 30 \text{ nm}$: normale Rohglasqualität
	B		B: $\sim 15 \text{ nm}$	$\sim < 15 \text{ nm}$: Bearbeitetes Glas
	A		A: $< 10 \text{ nm}$	
			VS: keine Schlieren sichtbar	VS1/VS2: Keine Schlieren in zueinander senkrechten Richtungen sichtbar

Measurement with Shadowgraphy

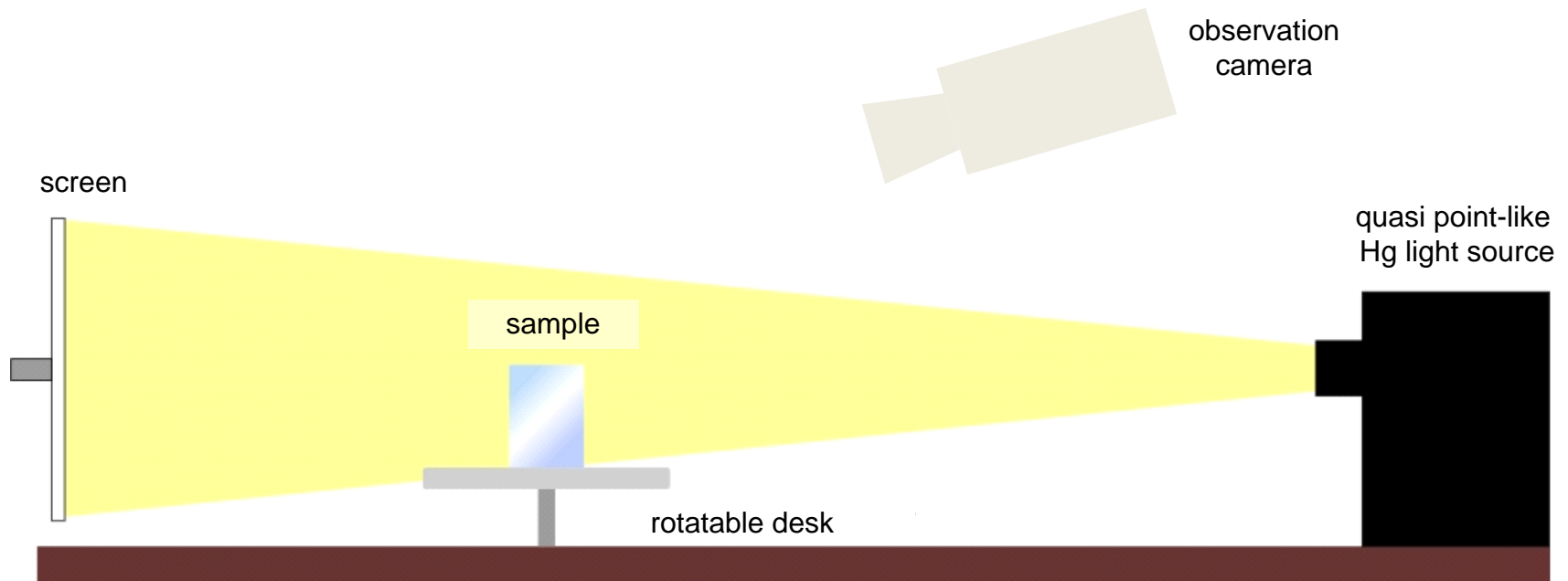


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- Advantages:
 1. Fast, cheap
 2. Simple setup
 3. Small requirements on sample surface quality
- Disadvantage:
 1. no quantitative calibration until now



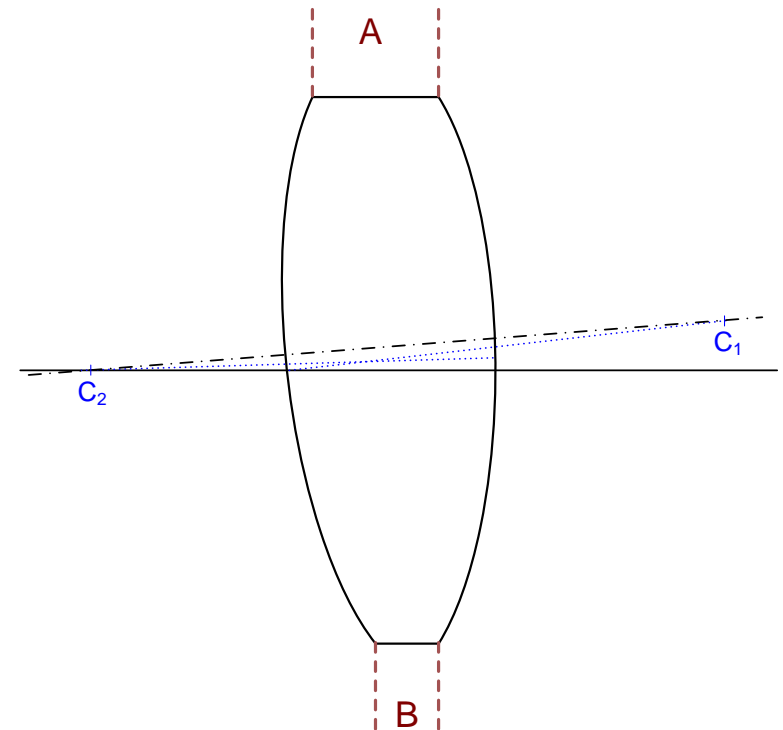
shadow
image



Centering Wedge Error

- Wedge error:
 - tilt of a single surface relative to the optical or mechanical axis.
 - Specification as tilt error of total indicator runout (TIR) in [mm]
 - angle value in rad: TIR / D (D diameter)
- The optical axis is the straight line through the two centers of curvature of the two spherical surfaces
- Mechanical axis:
defined by the cylindrical boundary of the lens
- Usually the optical and the mechanical axes do not coincide
- A wedge error must be specified only for one of the surfaces

$$TIR = A - B$$





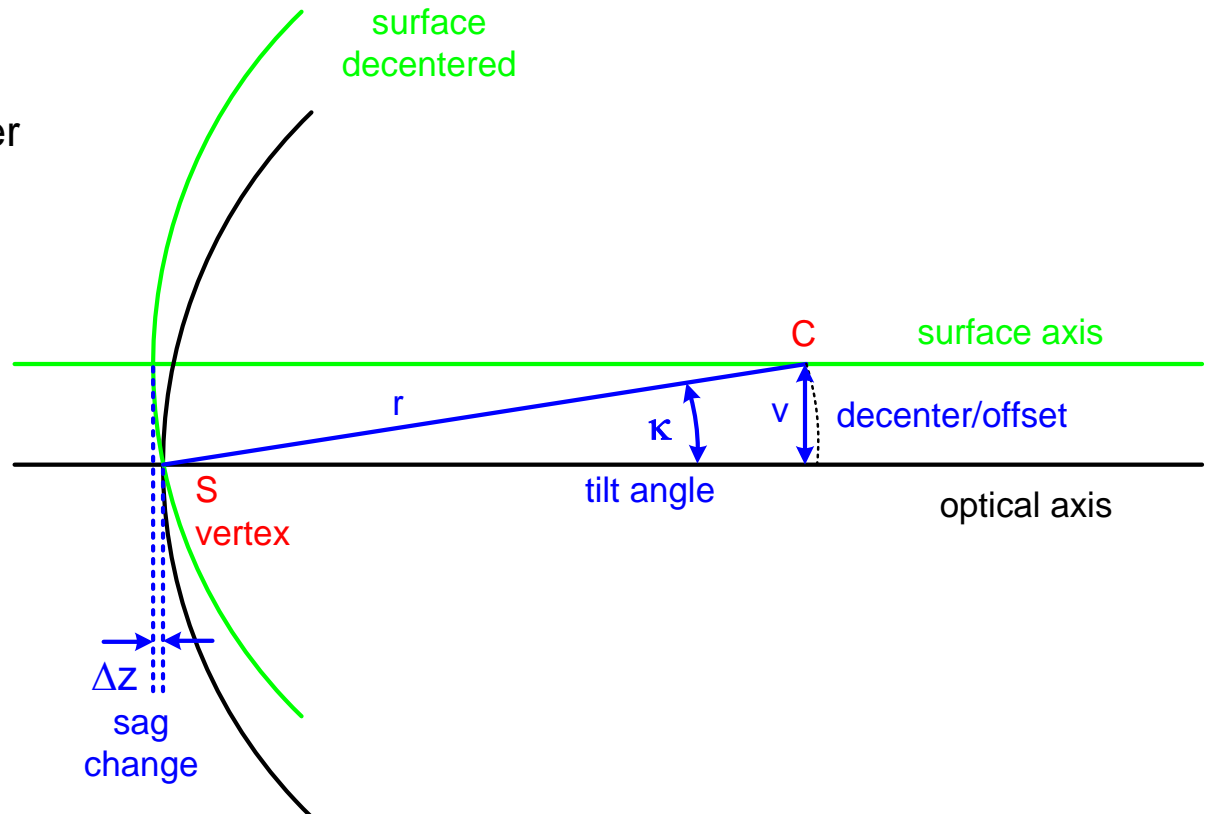
Centering of Spherical Surfaces

- Equivalence of decenter (offset) and tilt angle

$$\sin \kappa = -\frac{v}{r}$$

- Small change in sag (vertex position) in 2nd order

$$\Delta z = r \cdot (1 - \cos \kappa)$$



Rotation of a Spherical Surface

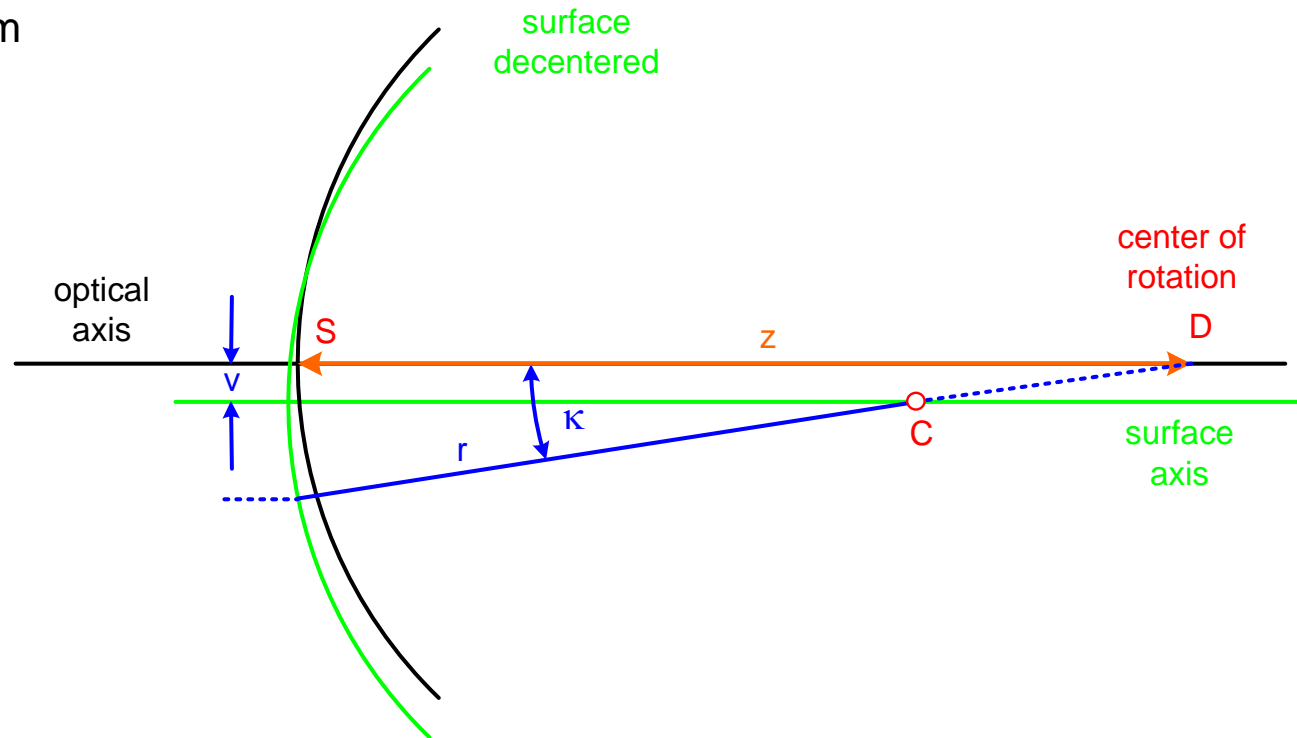


- Shift of center of rotation to D:
relation

$$\sin \kappa = -\frac{v}{r - z}$$

- Conversion of units from
radian to minutes

$$\begin{aligned} k &= \frac{\pi}{60 \cdot 180} \\ &= 2.9089 \cdot 10^{-4} \\ &\approx 3 \cdot 10^{-4} \end{aligned}$$



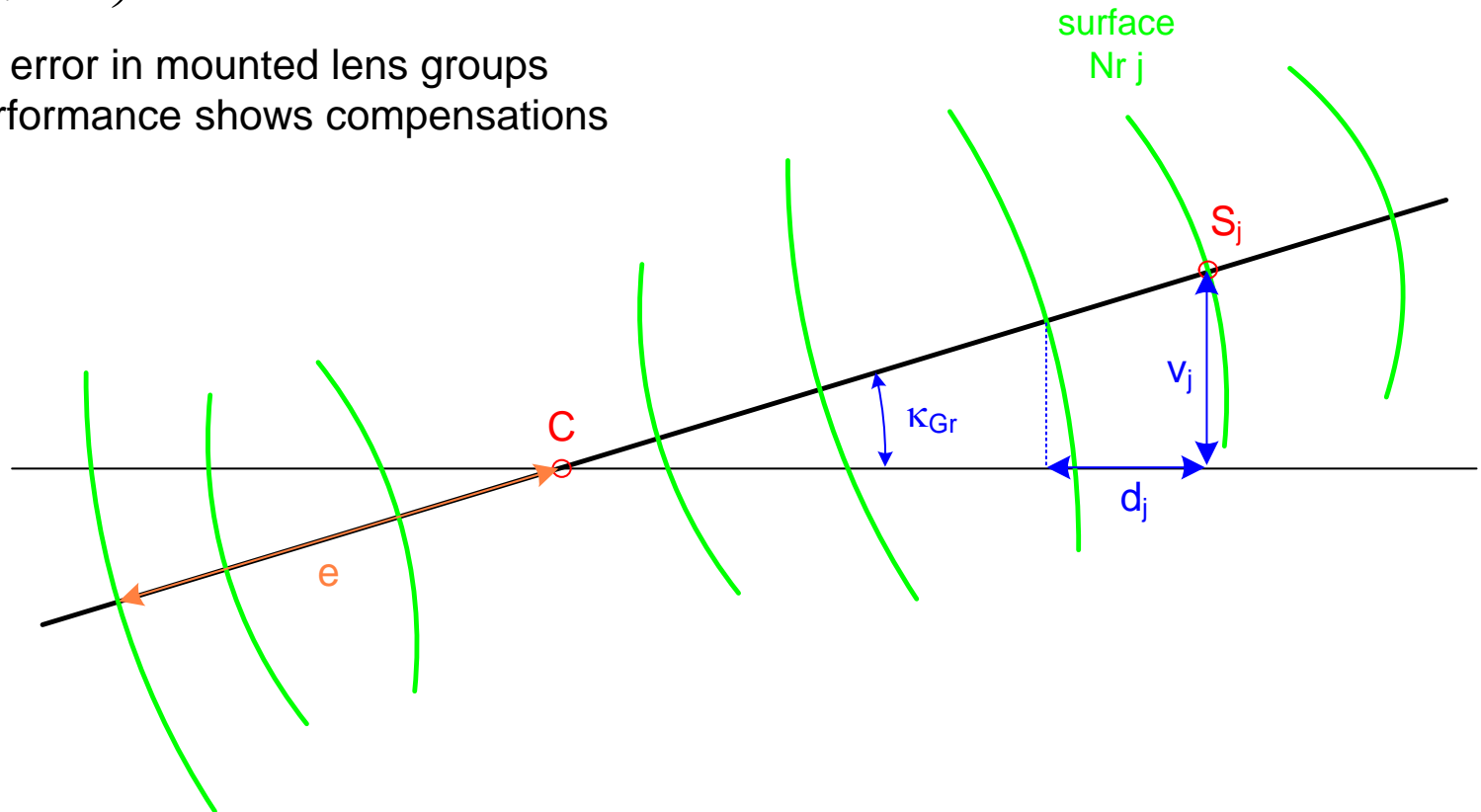
Rotation of a Group of Surfaces



- Rigid coupled sequence of surfaces
- Tilt with arbitrary location of center of rotation

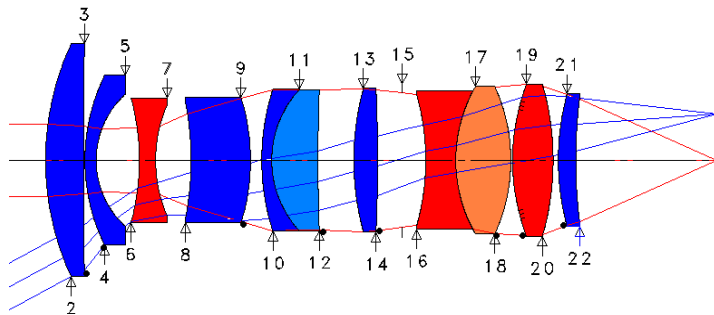
$$v_j = \left(e - \sum_{k=1}^j d_k \right) \cdot \sin \kappa_{Gr}$$

- Model for tilt error in mounted lens groups
- Effect on performance shows compensations



Centering tolerances in photographic lenses:

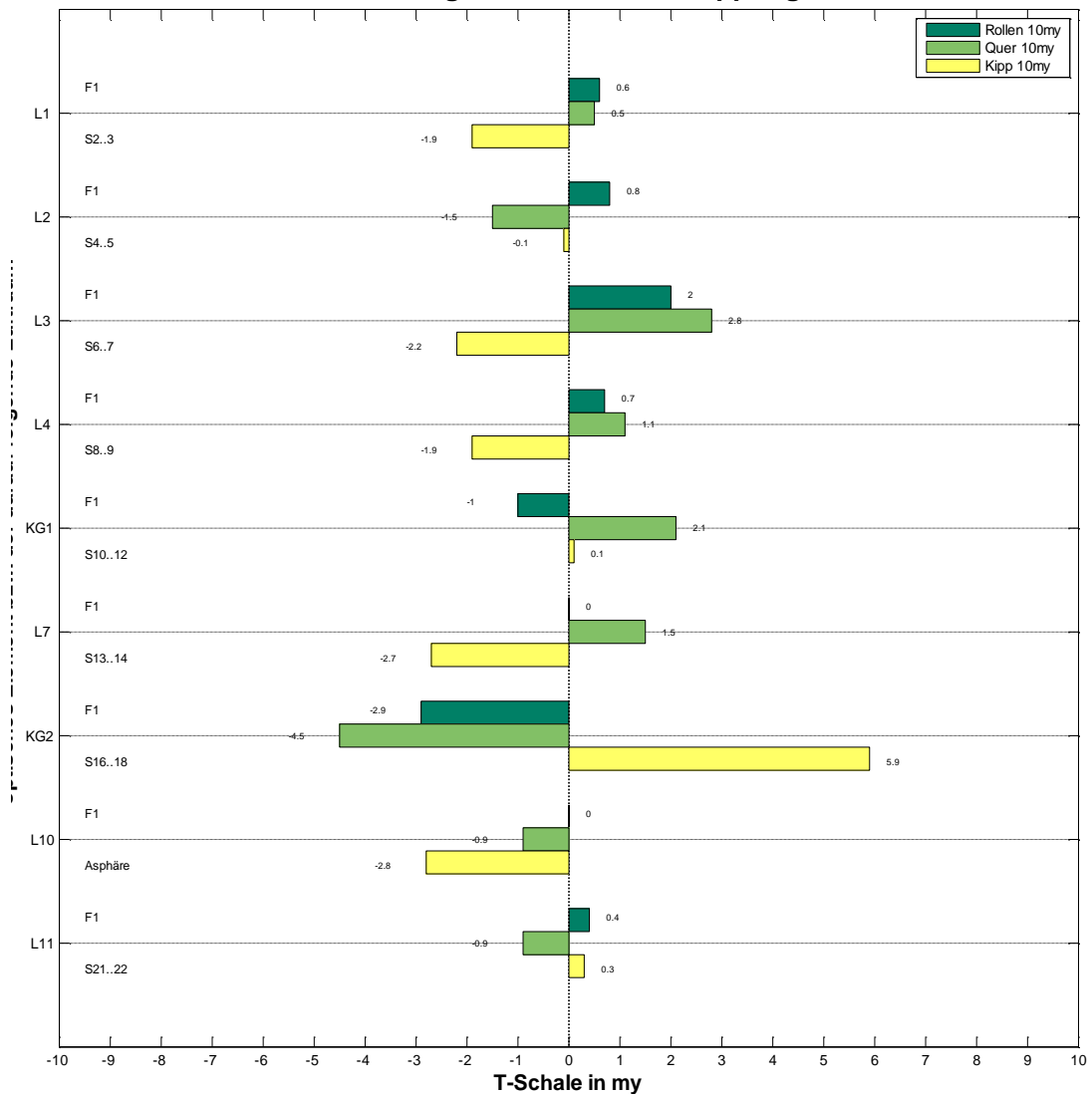
1. System layout



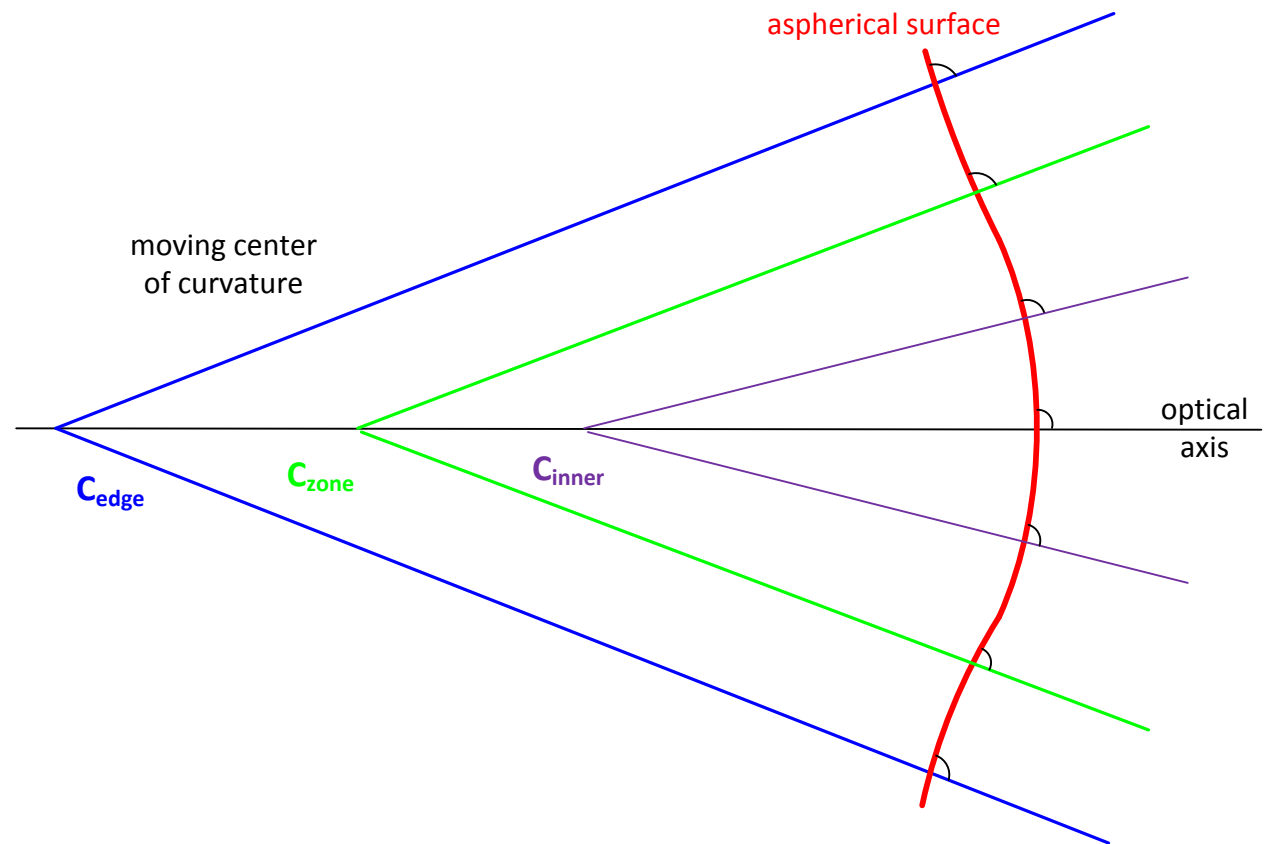
2. Tilt of image plane due to

- tilt (yellow)
- roll (green dark)
- decenter (green bright)

of lenses



- Asphere :
The location of the center of curvature moves with the radial surface position
- Conventional reflex light measurement in autocollimation is not possible

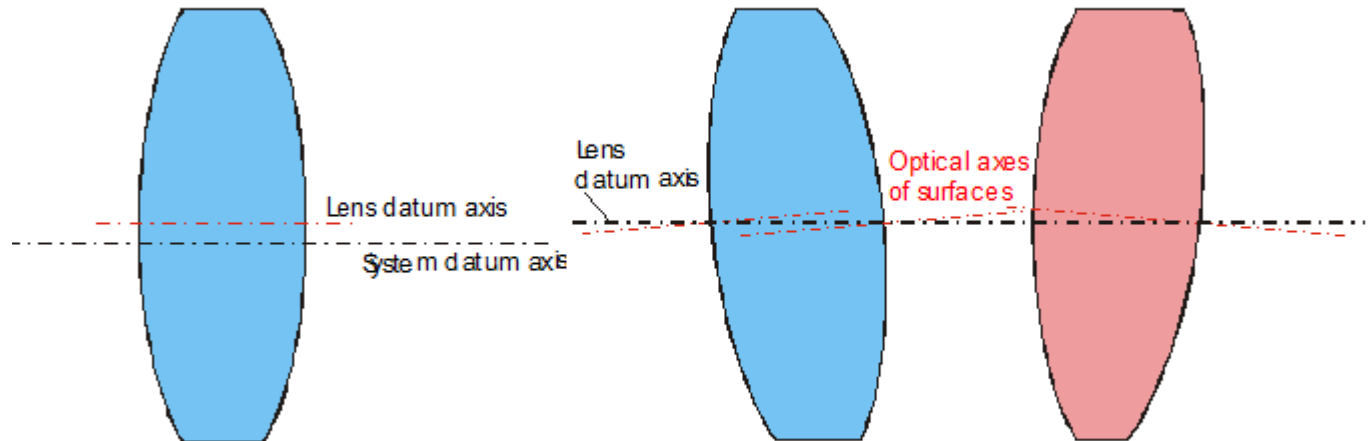


Centering Errors of Lenses



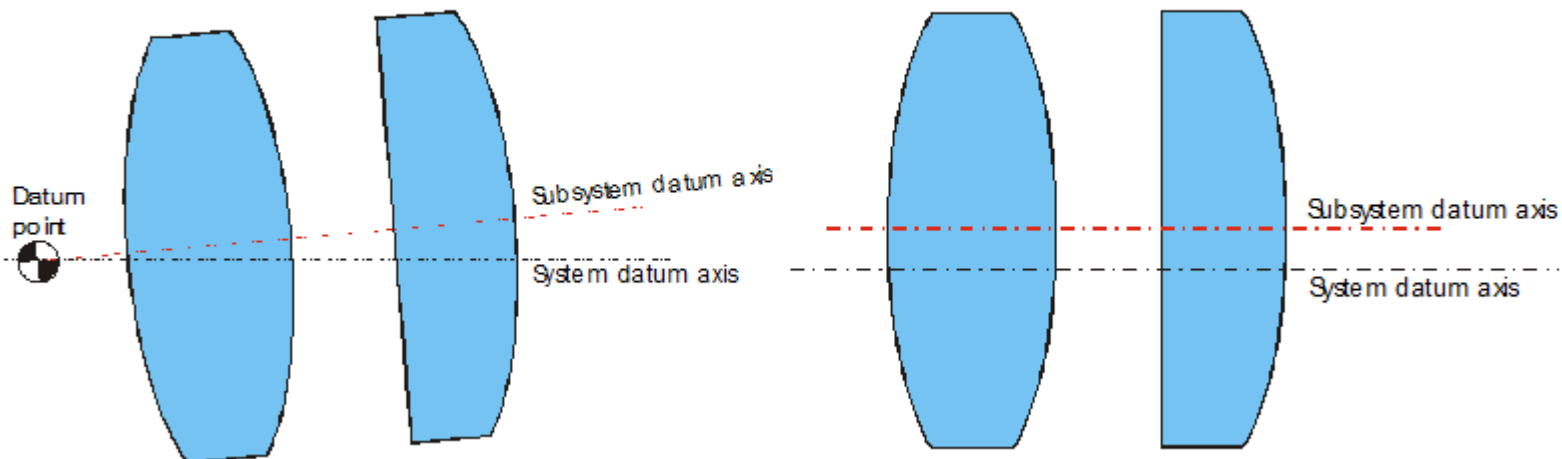
- Lens

1. Radial offset
2. Shearing
3. Wedge



- Lens group

1. Group tilt
2. Group offset



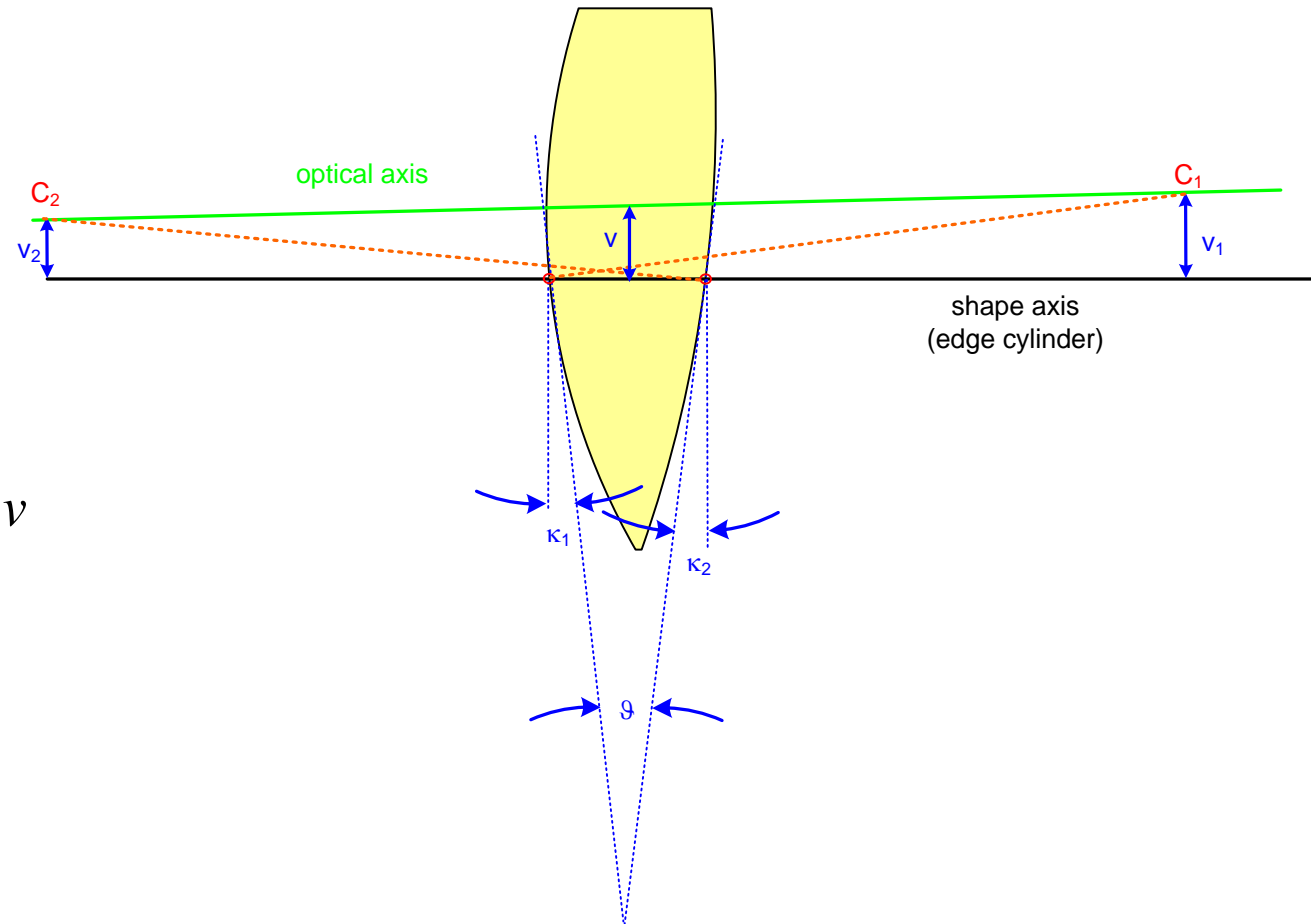
Wedge Angle of a Thin Lens



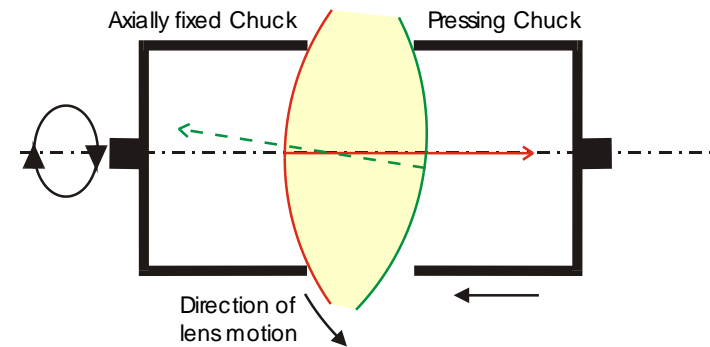
Thin lens with wedg error

$$\mathcal{G} = -\frac{v}{(n-1) \cdot f}$$

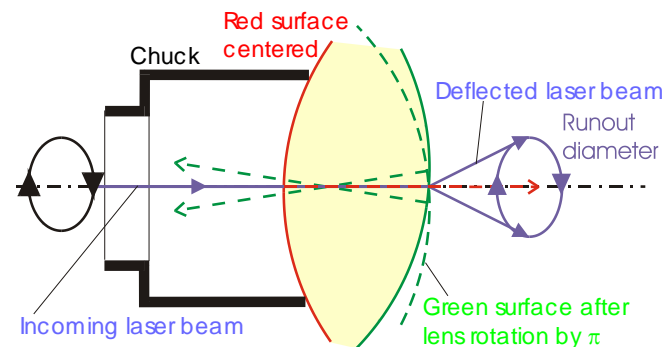
$$\mathcal{G} = \kappa_1 - \kappa_2 = \left(\frac{1}{r_1} - \frac{1}{r_2} \right) \cdot v$$



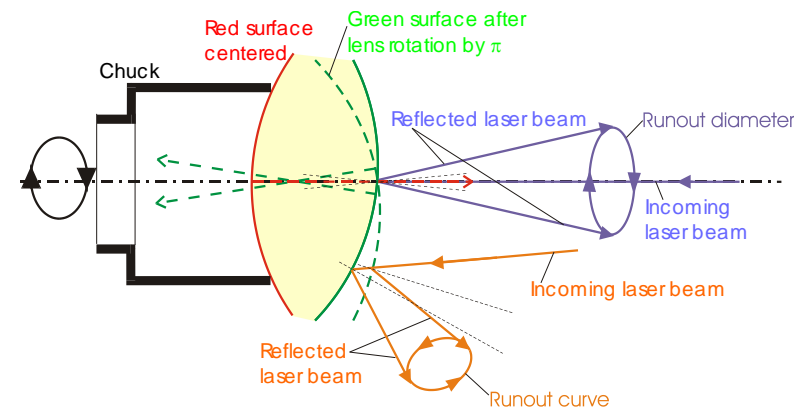
- Mechanical



- Ray in transmission



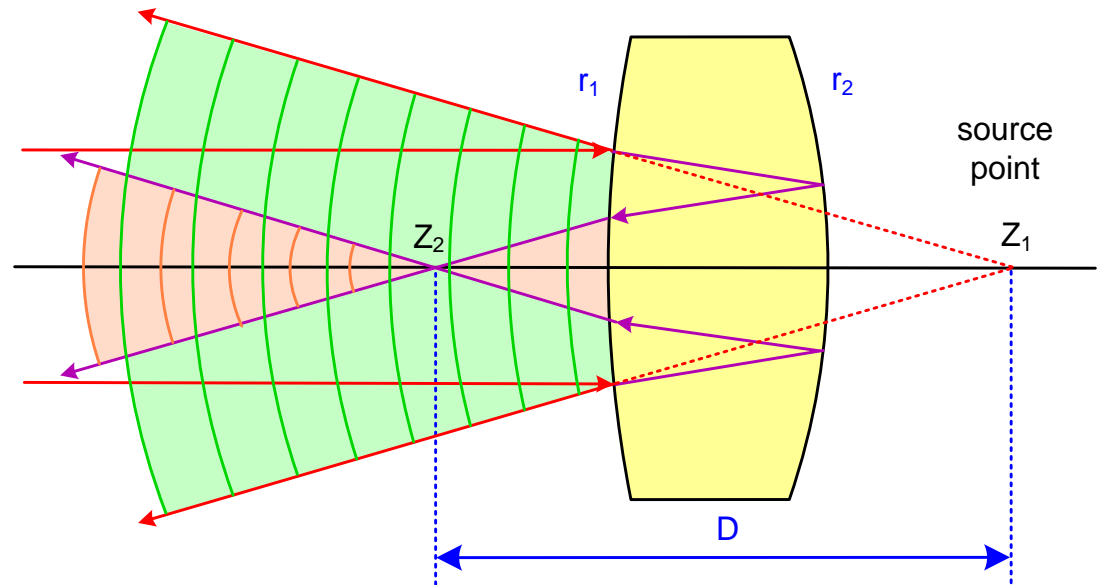
- Rays in reflection



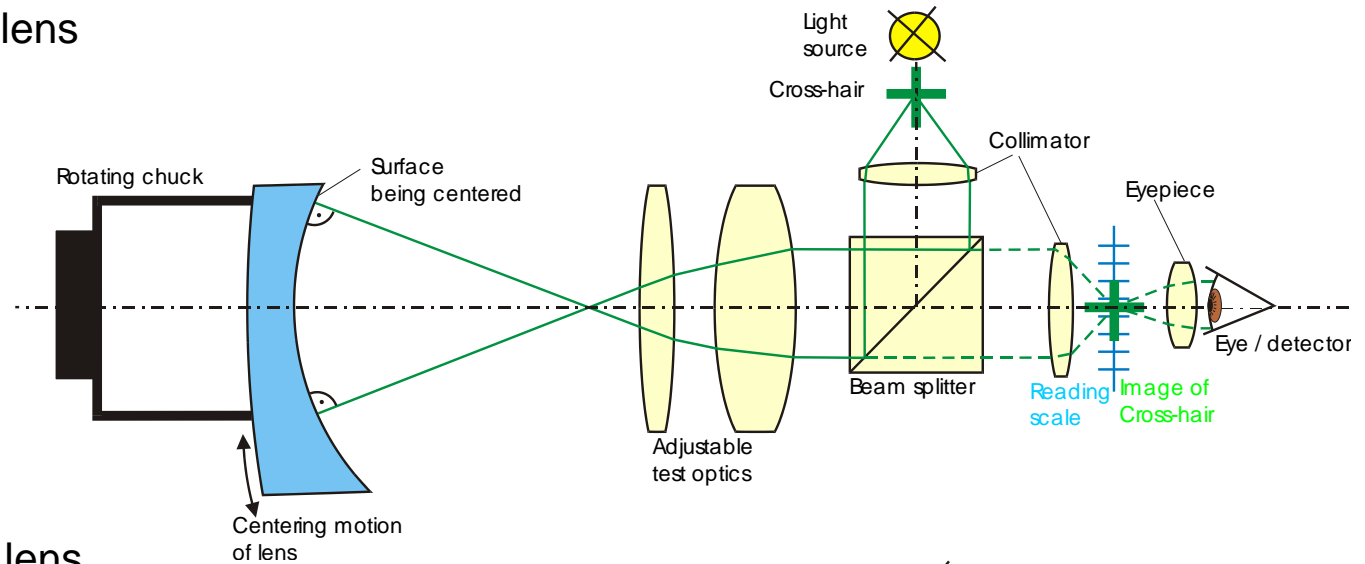
Centering of a Lens with Interferogram



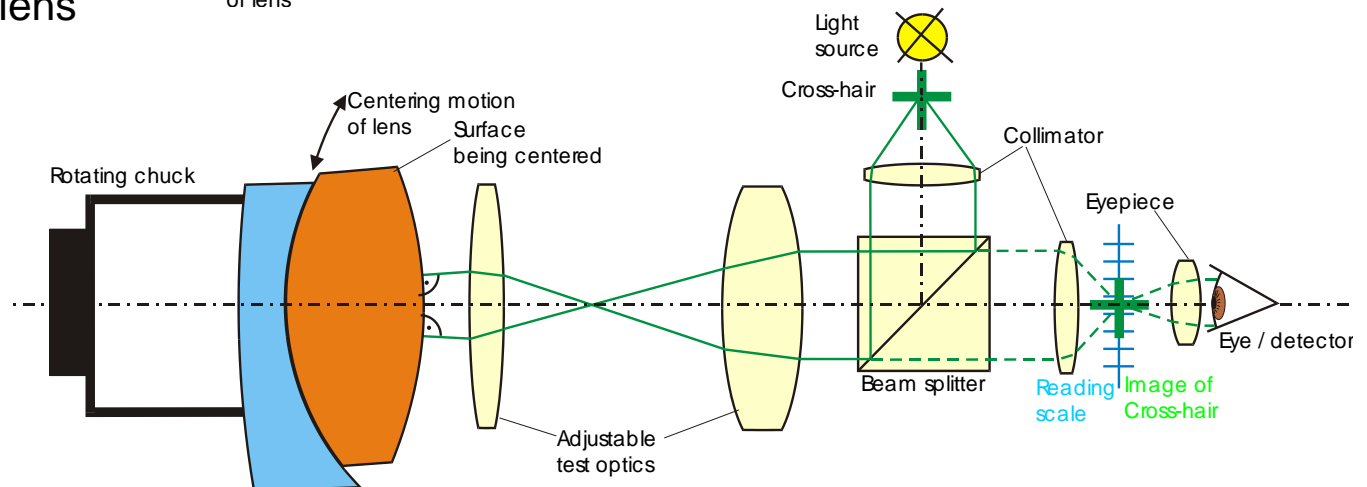
- Measurement of the centering of lens by inspection of the interferogram of front and rear surface



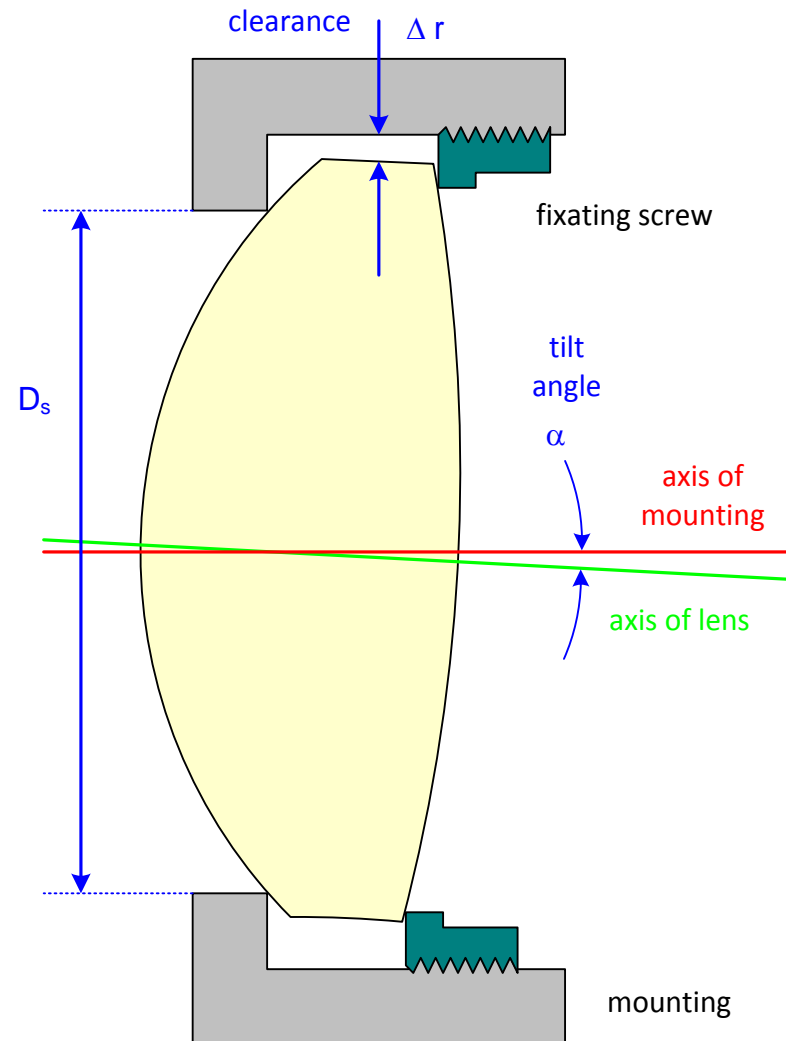
Centering carrier lens



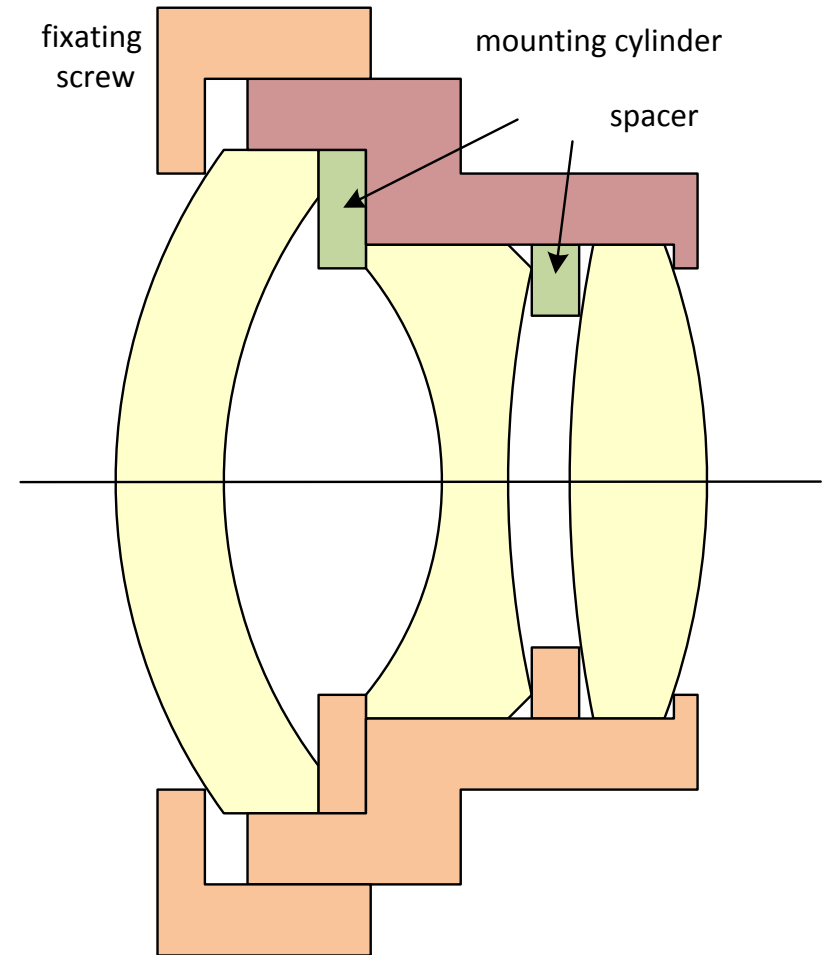
Adjusting second lens



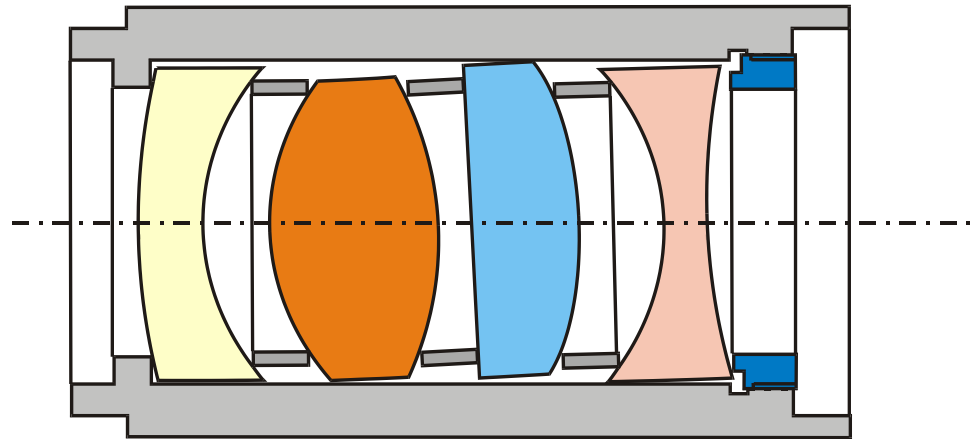
- Coupling optics – mechanics
Interface glass – metal
- Mechanical design of mountings and housing
- Typical options:
 1. Filling cylinder with fixating screw
 2. Cementing, later centering
 3. Lace / bordering
- Critical:
 - Centering tolerances
 - reference surfaces
 - analysis of complete geometry (kinematic)



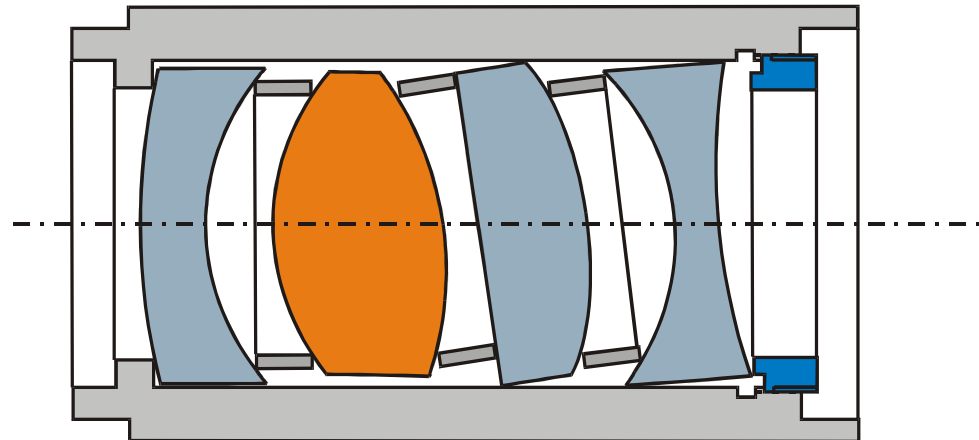
- Filling of lenses into mounting cylinder with spacers
- Accumulation of centering errors by transportation of reference
- Definition of lens positions by:
 1. mechanical play inside mounting
 2. fixating ring screw
 3. planarity of spacers



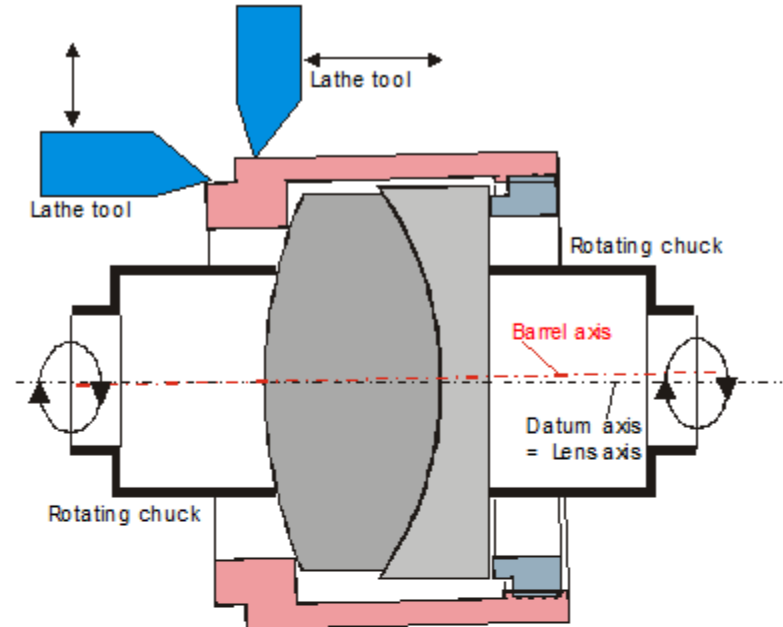
- Mechanical Play



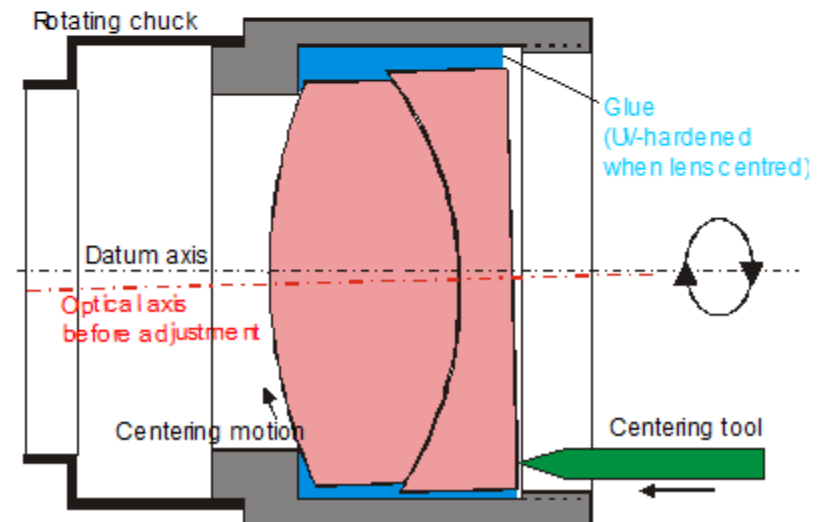
- Wedge errors



- Adjustment turning



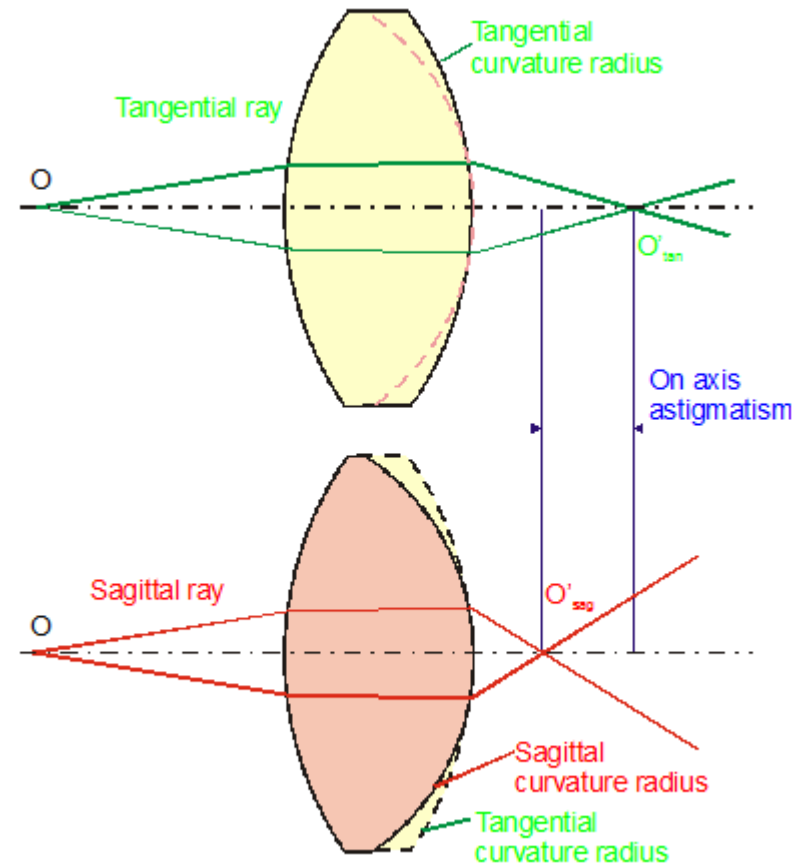
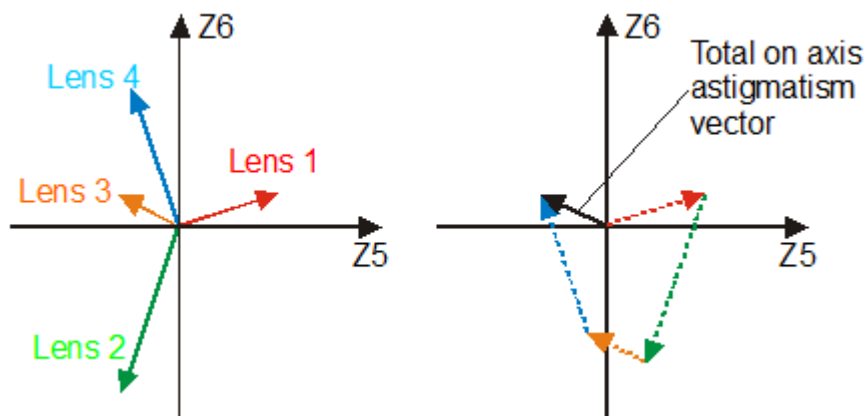
- Adjustment glueing



On-Axis Astigmatism

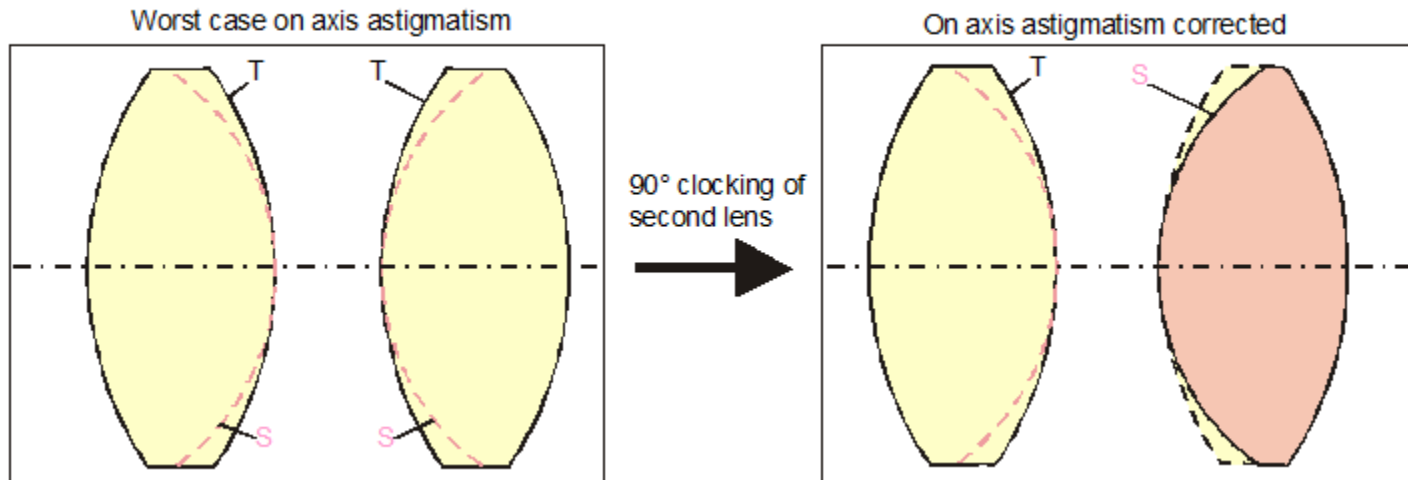


- On-axis astigmatism due to cylindrical irregularity
- Vectorial addition of astigmatism in systems



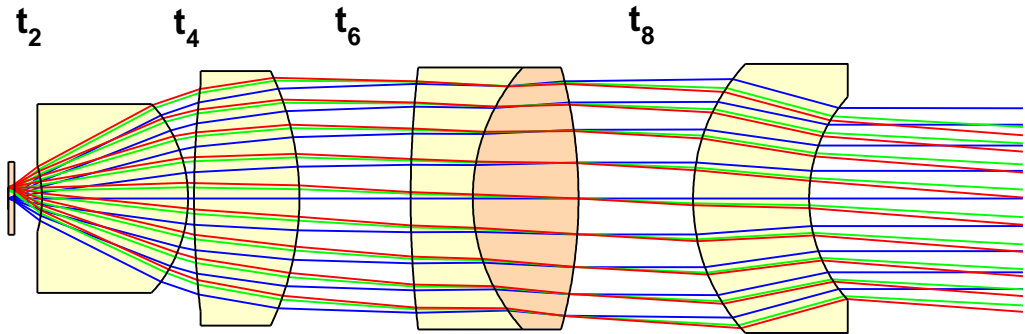
Correcting Astigmatism by Clocking

- Rotating of lenses around the optical axis
- Vectorial addition of individual astigmatism components



- Adjustment of air gaps to optimize spherical aberration
- Reduced optimization setup

$$c_j = c_{j0} + \sum_{k=1,4} \Delta c_j \cdot \frac{\partial c_j}{\partial t_k}, \quad j=2,4,6,8$$



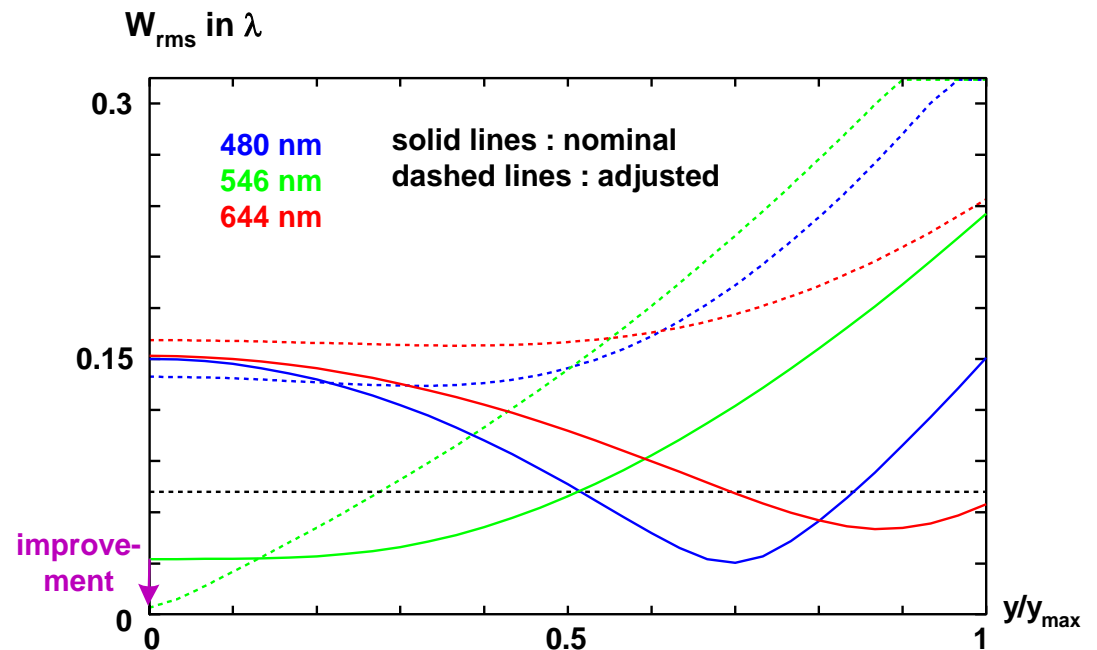
- Compensates residual aberrations due to tolerances (radii, thicknesses, refractive indices)

	d ₂	d ₄	d ₆	d ₈	c ₂₀	c ₄₀	c ₆₀	c ₈₀	W _{rms}
nominal	0.77300	0.17000	3.2200	2.0500	0.00527	-0.0718	0.00232	0.01290	0.0324
d ₂ varied	0.77320	0.17000	3.2200	2.0500	0.04144	-0.07586	0.00277	0.12854	
d ₄ varied	0.77300	0.17050	3.2200	2.0500	0.03003	-0.07461	0.00264	0.01286	
d ₆ varied	0.77300	0.17000	3.2250	2.0500	0.00728	-0.07367	0.00275	0.01284	
d ₈ varied	0.77300	0.17000	3.2200	2.0550	0.005551	-0.0717	0.00235	0.01290	
optimized	0.77297	0.16942	3.12670	3.2110	0.000414	0.00046	0.00030	0.01390	0.00468

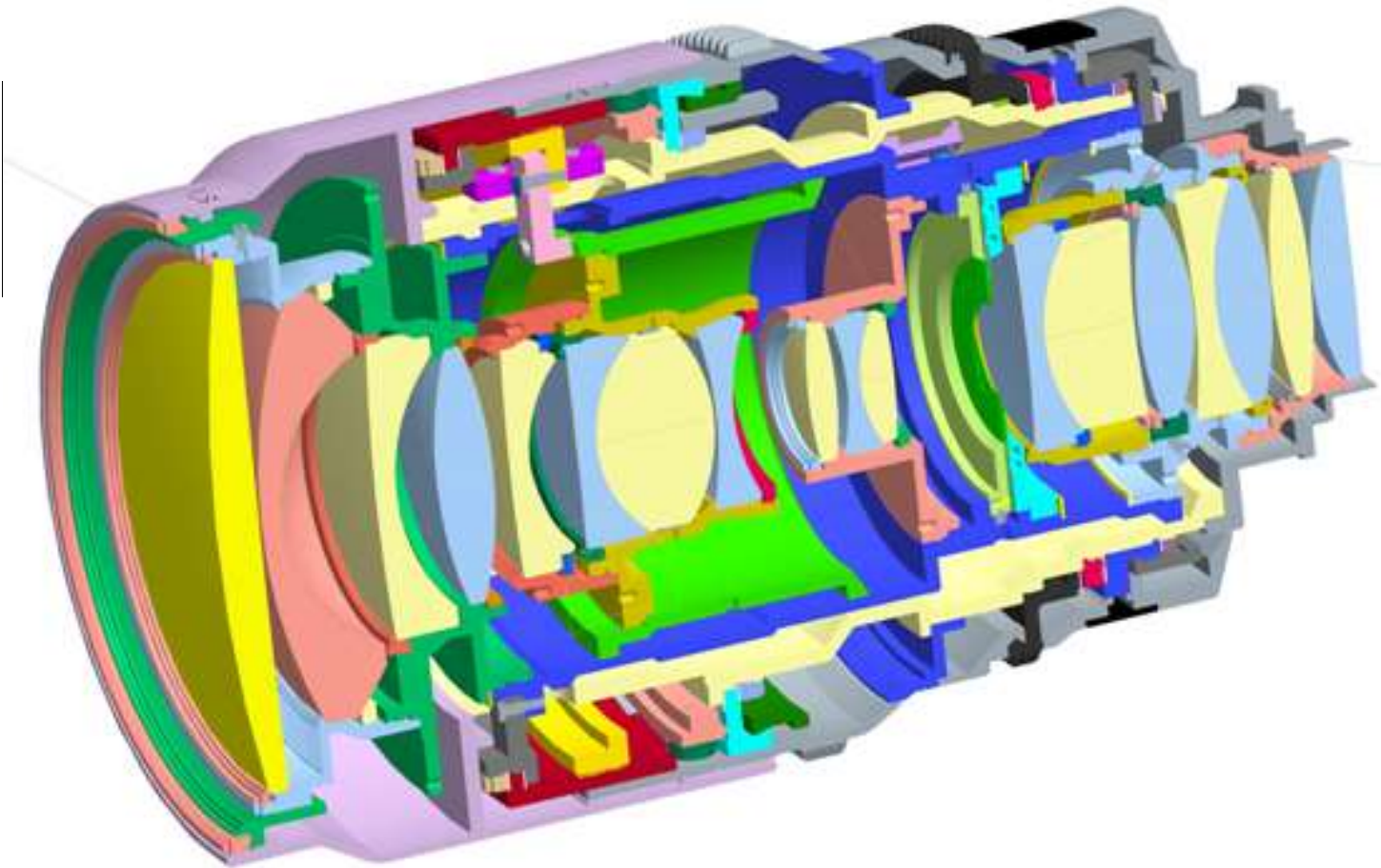
Adjustment of Objective Lenses



- Significant improvement for one wavelength on axis
- Possible decreased performance in the field



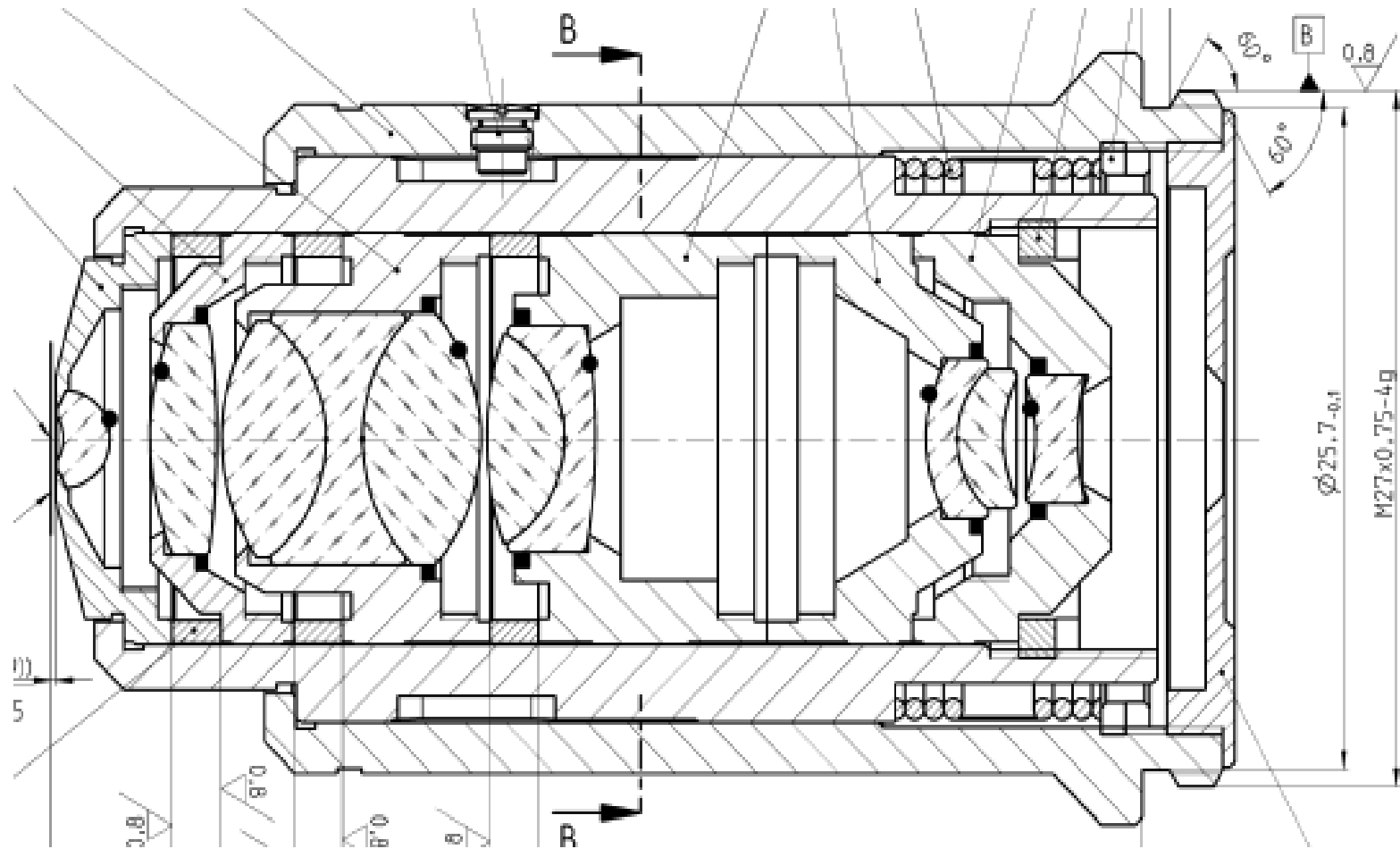
- Photographic lens: Digiprime 7



Drawing of Microscopic Lens with Housing



Institute of
Applied Physics
Friedrich-Schiller-Universität Jena



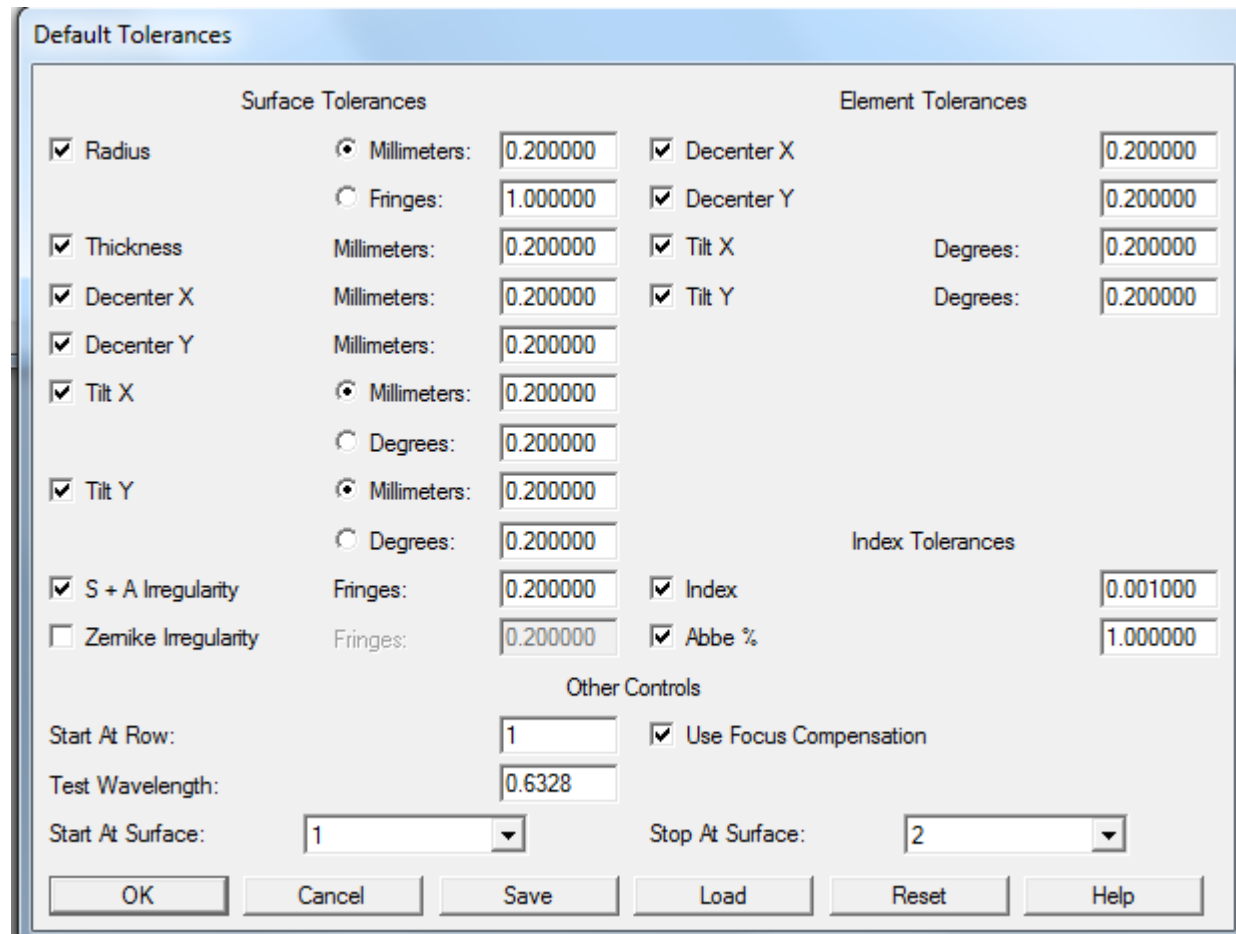
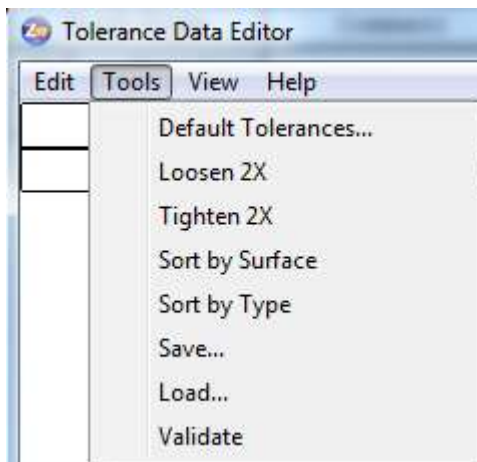
Mechanical Design of Photographic Lens



**Institute of
Applied Physics**
Friedrich-Schiller-Universität Jena



- Tolerance editor



The 'Default Tolerances' dialog box is shown, divided into three sections: Surface Tolerances, Element Tolerances, and Index Tolerances. It includes checkboxes for various tolerance types and input fields for their values.

Surface Tolerances		Element Tolerances	
<input checked="" type="checkbox"/> Radius	<input checked="" type="radio"/> Millimeters: 0.200000	<input checked="" type="checkbox"/> Decenter X	0.200000
	<input type="radio"/> Fringes: 1.000000	<input checked="" type="checkbox"/> Decenter Y	0.200000
<input checked="" type="checkbox"/> Thickness	Millimeters: 0.200000	<input checked="" type="checkbox"/> Tilt X	Degrees: 0.200000
<input checked="" type="checkbox"/> Decenter X	Millimeters: 0.200000	<input checked="" type="checkbox"/> Tilt Y	Degrees: 0.200000
<input checked="" type="checkbox"/> Decenter Y	Millimeters: 0.200000		
<input checked="" type="checkbox"/> Tilt X	<input checked="" type="radio"/> Millimeters: 0.200000		
	<input type="radio"/> Degrees: 0.200000		
<input checked="" type="checkbox"/> Tilt Y	<input checked="" type="radio"/> Millimeters: 0.200000		
	<input type="radio"/> Degrees: 0.200000		
<input checked="" type="checkbox"/> S + A Irregularity	Fringes: 0.200000	<input checked="" type="checkbox"/> Index	0.001000
<input type="checkbox"/> Zernike Irregularity	Fringes: 0.200000	<input checked="" type="checkbox"/> Abbe %	1.000000

Other Controls

Start At Row: 1 ☒ Use Focus Compensation

Test Wavelength: 0.6328

Start At Surface: 1 Stop At Surface: 2

Buttons: OK, Cancel, Save, Load, Reset, Help

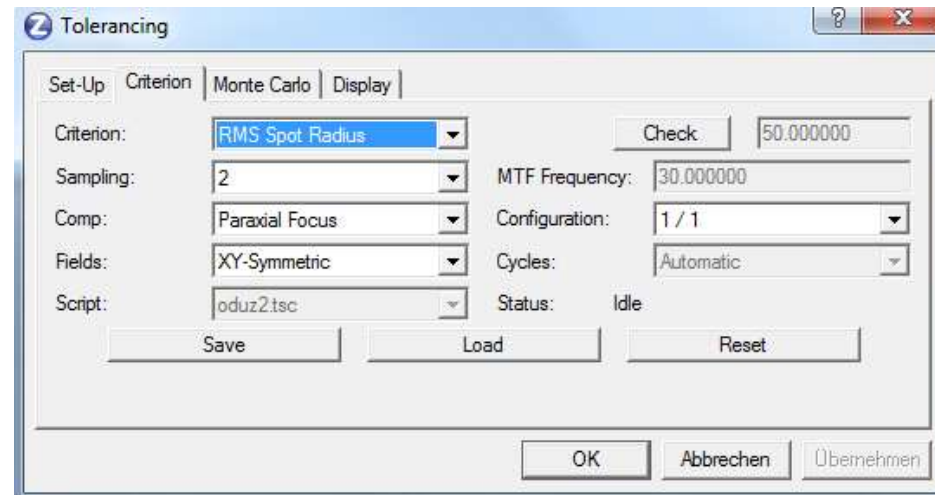
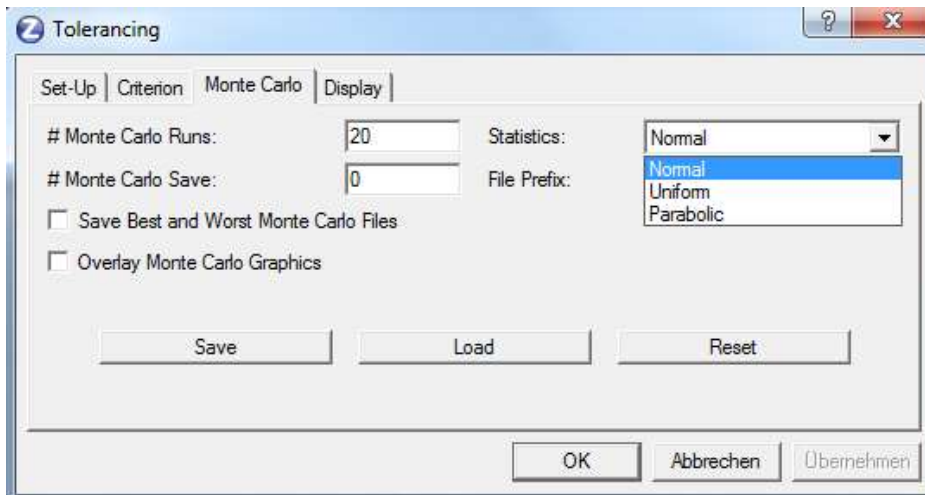
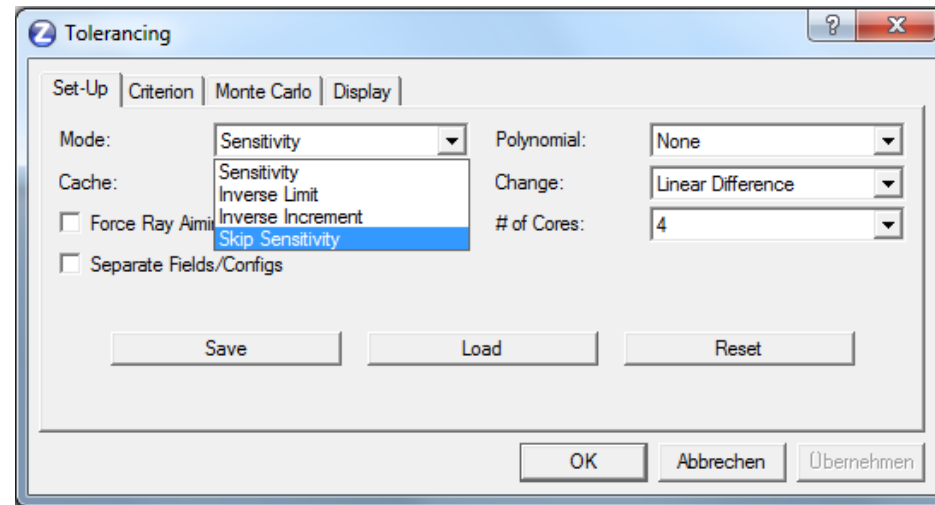
- Specification of tolerances:

Operators :	TRAD	Radius
	TFRN	Number of rings
	TTHI	Thickness
	TEDX	Element decenter x
	TETX	Element tilt x
	TSDX	Flächen decenter x
	TIRX	Flächen tilt x
	TIRR	Surface irregularity
	TIND	Refractive index
	TABB	Abbe number
	

Tolerancing in Zemax



- Specifying options:
 - statistics
 - model mode
 - criteria
 - compensators
 - ...



Tolerancing in Zemax



- Results
- Sensitivity and total performance

Worst offenders:

Type	Value	Criterion	Change
TSDX 5	-0.20000000	0.02526059	0.01762221
TSDX 5	0.20000000	0.02526059	0.01762221
TSDY 5	-0.20000000	0.02526059	0.01762221
TSDY 5	0.20000000	0.02526059	0.01762221
TSDX 7	-0.20000000	0.02437259	0.01673421
TSDX 7	0.20000000	0.02437259	0.01673421
TSDY 7	-0.20000000	0.02437259	0.01673421
TSDY 7	0.20000000	0.02437259	0.01673421
TIRX 7	-0.20000000	0.02379589	0.01615751
TIRX 7	0.20000000	0.02379589	0.01615751

Estimated Performance Changes based upon Root-Sum-Square method:

Nominal RMS Spot Radius	:	0.00763838
Estimated change	:	0.05195068
Estimated RMS Spot Radius	:	0.05958906

Compensator Statistics:

Change in back focus:

Minimum	:	-1.082992
Maximum	:	1.116496
Mean	:	0.000260
Standard Deviation	:	0.187537

Monte Carlo Analysis:

Number of trials: 20

Initial Statistics: Normal Distribution

Trial	Criterion	Change
1	0.01495279	0.00731442
2	0.04400927	0.03637090
3	0.03415890	0.02652053
4	0.04071841	0.03308004
5	0.04029339	0.03265501
6	0.02398819	0.01634981

Sensitivity Analysis:						
Type	Value	Minimum	Maximum	Value	Criterion	Change
TRAD 1	-0.20000000	0.00849681	0.00085843	0.20000000	0.00840246	0.00076408
TRAD 2	-0.20000000	0.00765278	1.4399E-005	0.20000000	0.00764493	6.5515E-006
TRAD 3	-0.20000000	0.01007277	0.00243440	0.20000000	0.00929790	0.00165952
TFRN 4	-1.00000000	0.00763885	4.6955E-007	1.00000000	0.00763791	-4.6440E-007
TRAD 5	-0.20000000	0.01331290	0.00567453	0.20000000	0.01387767	0.00623929
TRAD 7	-0.20000000	0.01144217	0.00380380	0.20000000	0.01129590	0.00365752
TFRN 8	-1.00000000	0.00763763	-7.4458E-007	1.00000000	0.00763912	7.4594E-007
TRAD 9	-0.20000000	0.00850263	0.00086425	0.20000000	0.00910557	0.00146720
TRAD 10	-0.20000000	0.00764407	5.6948E-006	0.20000000	0.00763532	-3.0531E-006
TRAD 11	-0.20000000	0.00765819	1.9813E-005	0.20000000	0.00792170	0.00028332
TTNI 1 2	-0.20000000	0.00762323	-1.5148E-005	0.20000000	0.00768413	4.5758E-005
TTNI 2 5	-0.20000000	0.00824536	0.00060698	0.20000000	0.00817407	0.00053569
TTNI 3 5	-0.20000000	0.00993570	0.00229732	0.20000000	0.01021174	0.00257337
TTNI 4 5	-0.20000000	0.00985836	0.00221998	0.20000000	0.01016222	0.00252384
TTNI 5 6	-0.20000000	0.00757994	-5.8439E-005	0.20000000	0.00770451	6.6137E-005
TTNI 6 9	-0.20000000	0.00938733	0.00194896	0.20000000	0.00897468	0.00133631
TTNI 7 9	-0.20000000	0.00790577	0.00026739	0.20000000	0.00852506	0.00088668
TTNI 8 9	-0.20000000	0.00790654	0.00026816	0.20000000	0.00850526	0.00086688
TTNI 9 11	-0.20000000	0.00771691	7.7930E-005	0.20000000	0.00814041	0.00050203
TTNI 10 11	-0.20000000	0.00763321	-5.1669E-006	0.20000000	0.00783020	0.00019182
TEDX 1 2	-0.20000000	0.00937533	0.00173695	0.20000000	0.00937533	0.00173695
TEDY 1 2	-0.20000000	0.00937533	0.00173695	0.20000000	0.00937533	0.00173695

Number of traceable Monte Carlo files generated: 20

Nominal	0.00763838		
Best	0.01495279	Trial	1
Worst	0.05384504	Trial	20
Mean	0.03581970		
Std Dev	0.00958822		

Compensator Statistics:

Change in back focus:

Minimum	:	-1.576642
Maximum	:	1.508236
Mean	:	0.085907
Standard Deviation	:	0.838905

90% >	0.04780477
80% >	0.04316296
50% >	0.03725716
20% >	0.02545120
10% >	0.02369940

Tolerancing in Zemax



- Graphical overlay of tolerance influence

